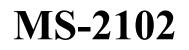
# MASTERTRACE



HEAT TRACING CONTROL

# **OPERATOR'S MANUAL**



# MS-2102

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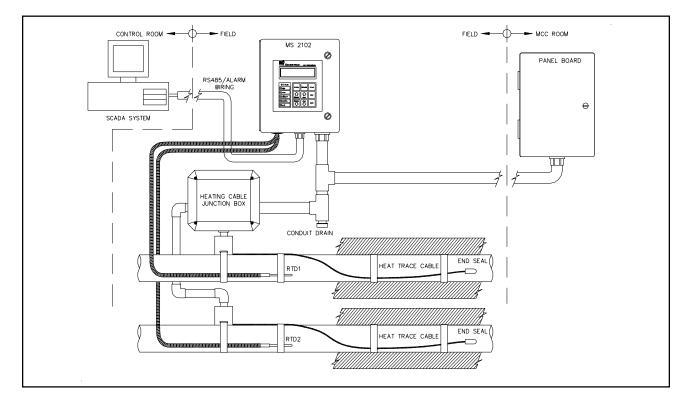
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# Introduction

The MS-2102 two-point heat tracing controller uses a microprocessor and is intended for stand-alone heat trace applications. It can be for use with mineral-insulated, self-regulating or constant-wattage cable for freeze protection, process control and instrument tracing. The MS-2102 is intended for indoor or outdoor installations in ordinary or hazardous locations.

MS-2102 offers many advantages over other heat tracing control schemes, which generally use some combination of mechanical thermostats, custom-built panels or programmable controls to provide control, monitoring and alarm functions. Budgetary constraints usually limit the degree of system fault monitoring to less than optimal levels. This results in periodic costly process shutdowns due to process or hardware malfunctions. Equipment reliability concerns often force plant procedures to include annual thermostat performance checks to ensure that the device is still operating as intended. This can be a tedious, labour intensive job. A MS2102 Control Module is mounted near the pipes being traced to monitor the heater points. This Control Module can communicate with a single master unit to give complete system monitoring and control from a convenient location. Up to 32 Control Modules can be monitored on a RS485 data highway to a centrally located master. By connecting Control Modules to a data highway, the MS-2102 can immediately flag alarms caused by heat tracing malfunctions, altered setpoints and monitor actual values from a central location. Each local Control Module is completely independent and will continue to function if the master fails or if the communication link fails. This ensures maximum reliability and minimizes vulnerability in the event of a hardware failure. Additional points can easily be added at any time as easily as a mechanical thermostat can be installed. Unlike control schemes using programmable controllers, no software development is required. The complete system is operational as soon as it is installed.





# Chapter 1 Product Overview

Specifications <sup>1</sup>		Contrast:	Adjustable by potentiometer
Models: MS-2102, M	IS-2102-E3, MS-2102-BAC, MS-2102-BAC1,	Panel Indicators:	Power on, Heater on, Communication active, System fail, Process alarm
MS-2102-E3	-BAC, MS-2102-E3-BAC1, MS-2102-ETH,	Security:	Controller parameters switch-protected
MS-2102-ET	H1, MS-2102-E3-ETH, MS-2102-E3-ETH1	5	controller parameters switch protectes
Temperature Input		Environment	
Range:	-50 to +500°C (-58 to 932°F)	Approvals:	CSA C/US, Class I, Div. 2, Groups A, B
Accuracy:	±2°C		C, D; Class I, Zone 2, Groups IIC;
Repeatability:	±1°C		Class II, Div. 2, Groups F & G; Class II
RTD:	Two, 100 ohm platinum, 3-wire RTD	Operating Temperature:	-40°C to +50°C
	20 ohms maximum lead resistance	Conformal Coating:	Boards conformal coated for hostile environments
Heater Switching		Enclosure	environments
Configuration:	Two circuit, single-pole, one SCR per		Madala mith antian E2. Nama 4X
	circuit, 800 amp 1 cycle inrush	Type:	Models with option E3: Nema-4X stainless steel, painted black
Ratings:	85-280Vac, 30A continuous		Models without option E3: Nema-4X
Line Frequency:	50 or 60Hz		steel, painted black
Current Measurement: GF Measurement:	0.1 to 30A 3%±0.2A 10 to 1000mA 5%±2mA	Size:	10"Hx8"Wx6"D
Voltage Measurement:	0 to 300Vac $3\%\pm 2$ (only for heater 1)	Features:	Quick release latches to open door
•	$0$ to $300$ vac $3/0\pm 2$ v (only for heater 1)		Flat aluminum plate to act as heatsink
Control Power			and mounting flange for mounting on
Power Requirement:	Control power from heater 1 voltage		Uni-Strut.
	85-280VAC, 10VA max		One 3/4" conduit knockout for power
Protection:	Control power from heater 1 voltage		and three 1/2" conduit knockouts for RTI
	protected by 2A fuse		and signal wiring.
	MOV transient protection	Alarm Output	
Communication		Alarm:	Programmable for NO or NC contact
Port:	1 Serial network connection		One Mechanical (dry) contact
Type:	RS485	Alarm Rating:	Mechnical contact: 30Vdc/100mA,
Protocol:	Modbus® RTU.	-	120Vac/0.52A, 62.5W M
Transmission Rate:	600,1200, 2400, 4800, 9600 baud.	Alarm Output:	LED Indicator: 5Vdc/50mA
Interconnect:	2-wire, shielded, twisted pair.	Alarm Function	
Highway Distance:	4,000 feet without repeater.	Temperature:	High Temp Alarm, Low Temp Alarm
Modules per Highway:	32 Control Modules.	Current:	Low Current Alarm, High Current Alar
BACnet/IP Ethernet (	Communication	Ground Fault Current:	Ground Fault Current Alarm
	options BAC/BAC1		Ground Fault Current Trip
	& assembled MasterTrace Modbus to	Voltage:	Low Voltage Alarm
	gateway, separated from MS-2102 module	Hardware:	Self-Check Failure, Relay Failure, RTD
Serial Connection:	To be connected to serial ports @ 9600 baud on modules via RS485 cable		Open, RTD Short
Ethernet Connection:	To be connected to Ethernet network	User-Definable Optio	ns
Enclosure:	via Ethernet cable FRP enclosure with option BAC1 only	Heater Status:	Enable or Disable
	1 2	Heater Name or Tag:	16 Character Alphanumeric
MODBUS TCP Ethern		Temperature Units:	°C or °F
	options ETH/ETH1	Proportional Control:	on or off
	& assembled MasterTrace Modbus to	Deadband:	1 to 50C° (2 to 90F°)
	gateway, separated from MS-2102 module	PowerLimit:	0.1 to 30A, off
Serial Connection:	To be connected to serial ports @ $1200 \sim$	TraceCheck:	1 to 24hrs, off
Ethernet Connection:	9600 baud on modules via RS485 cable To be connected to Ethernet network	Temperature Setpoint:	-50 to 500°C (-58 to 932°F), off, none
Ethernet Connection.	via Ethernet cable	High Temp Alarm:	-50 to 500°C (-58 to 932°F), off
Enclosure:	FRP enclosure with option ETH1 only	Low Temp Alarm: High Current Alarm:	-50 to 500°C (-58 to 932°F), off 0.1 to 30A, off
Measured Values	1 5	Low Current Alarm:	0.1 to 30A, off
Temperature:	-50 to 500°C (-58 to 932°F)	Ground Fault Alarm:	10 to 1000mA, off
Minimum Temperature:	-50 to 500°C (-58 to 932°F)	Ground Fault Trip:	10 to 1000mA, off
Maximum Temperature:	· · · · · · · · · · · · · · · · · · ·	Low Voltage Alarm:	85V to 300V, off
Heater Current:	0.1 to 30A	RTD Fail-safe:	Heater On or Heater Off
Ground Fault Current:	10 to 1000mA	Override:	On or Off
Min. Heater Voltage:	85 to 300Vac	Alarm Contacts:	NO or NC for mechanical contact
Max. Heater Voltage:	85 to 300Vac	Alarm Light:	Alarm on, Alarm off, Flash during alarm
Power Consumption:	0 to 1,000 MWh	č	then on, Flash during alarm then off
Operating Cost:	0 to \$1,000,000.00	Ground Fault	-
User Interface		Maximum Trip Time:	7.4 seconds
Display:	16-character x 2-line LCD display	maximum riip rime:	/.+ 5000105
Keypad:	9 tactile keys, polyester faceplate	1. This is a pricise sp	ecification for MS2102 controller. F
9 f	- Setpoint, measured, status		could be some variations.
	- Message Up, Message Down	maners, there	coura de some variations.
	- Message Op, Message Down		

#### Inputs

- · 2-RTD Sensors, one per circuit
- 1-Override

#### Monitoring

- RTD Temperatures
- Heater Current
- Heater Voltage
- GF Current

#### Alarms

- Low and High Current
- Low and High Temperatures
- GF Alarm
- GF Trip
- Relay Failure
- Sensor Failure
- Self-Test Failure

#### Outputs

- 1-Mechnical (dry) Contact
- 1-LED Alarm Indicator

#### Statistics

- Minimum and Maximum Temperatures
- Maximum Current
- Maximum Ground Fault
- Energy (MWh)
- Energy Cost

## Control

- Temperature (On/Off- Deadband)
- Temperature Proportional
- PowerLimiting

### Early Warning (TraceCheck)

- Low and High Current
- GFAlarm
- GF Trip

#### Communications

- 1-RS485
- Modbus Protocol

#### Environment

- CSA Certified for Hazardous Locations
- Weatherproof, NEMA-4X Enclosure
- -40°C to +50°C Operating Temperature Range (LCD: -20°C to +50°C)

#### **User Interface**

- 32 Character LCD Display
- LED Indicators on Faceplate
- Clear, English Language Messages
- Intuitive Message Structure
- Tactile Keys
- Access Security

# **Using This Manual**

Detailed information relating to switch and output ratings, accuracy and so forth are detailed in *Chapter 1 Specifications. Chapter 2 Installation* discusses important mounting and wiring issues for reliable operation. *Chapter 3 Getting Started* provides a step-by-step tutorial for a heat trace application. The remainder of this manual should be read and kept for reference to provide the maximum benefit of the MS-2102.

# Conventions

The following conventions are used in this manual.

- 🖉 User Changeable Values
- Retrieved Data
- [] Key Press

#### **Shipping Content**

MS-2102 Heat Trace Controller MS-2102 Instruction Manual with Warranty Card Controller functions are controlled by a microprocessor that measures all analog signals and logic inputs, control heater outputs and alarm contacts, and reads all user input including communications and outputs to the faceplate display and LEDs. Consult the hardware block diagram in figure 1.5 for details. The remainder of this chapter describes the algorithms and operation of some of the controller functions.

# **RTD Sensing**

An RTD changes its resistance in a precision relationship to temperature. This resistance is sensed by passing a constant current through the RTD and measuring the resulting voltage across the RTD (resistance = voltage/ current). The voltage appearing across RTD1 terminals 6-8 (designated to heater 1) or RTD2 (designated to heater 2) terminals 10-12 also includes the resistance of the interconnecting wiring to the RTD, which varies with wire length, size and ambient temperature. By using a threewire sensing scheme and a lead resistance compensation circuit, the lead resistance is cancelled out to give a voltage proportional to the true RTD sensor temperature.

RTDs respond in a known but non-linear fashion to temperature, which if uncorrected could lead to significant errors over the temperature range of the controller. Consequently, some means are needed to convert the input voltage to a linear and useful range. The CPU applies gain, offset and non-linearity corrections through a linearization algorithm.

Figure	1 2 Cycl	e Modulat	ion - 10	Cycle I	Frame
rigure 1	1.2 Cyci	e mouulai	1011 - 10	Cycle I	riame

# Current, Ground Fault and Voltage Sensing

Current transformers and high impedance voltage dividers are used to scale-down the incoming heater current, ground fault current and voltage. All three signals are then passed through a full wave rectifier and filter to obtain a DC signal. The DC signals are then converted to digital values by a 10 bit A/D converter before finally being passed on to the CPU for analysis.

Each of the three DC signals are sampled 300 times with zero cross synchronization so that the sampling covers an exact span of ten power cycles. This is to ensure that heater current values are consistently measured when the heater output cycle is modulated by the powerlimit and proportional control functions.

# Powerlimit

The powerlimit function allows the heater to operate below its rated power by cycle modulation. Cycle modulation is accomplished by controlling the integral number power cycles into the heater over a periodic time frame. The MS-2102 uses a ten cycle time frame. The integral number of power cycles per time frame is called a *duty cycle*. With a ten cycle time frame, there are ten duty cycles possible. For each duty cycle, there is a fixed pattern that defines the number of power cycles in which the heater is on and off. This is shown in figure 1.2:

DUTY CYCLE	CYCLE ON	CYCLE OFF	SWITCHING PATTERN
0%	0	10	
10%	1	9	
20%	2	8	
30%	3	7	
40%	4	6	
50%	5	5	
60%	6	4	
70%	7	3	$0 \xrightarrow{1} 2 \xrightarrow{3} 4 \xrightarrow{5} 6 \xrightarrow{7} 8 \xrightarrow{9} 10$
80%	8	2	$p \rightarrow 1$ $2 \rightarrow 3$ $4 \rightarrow 5 \rightarrow 6 \rightarrow 7$ $8 \rightarrow 9 \rightarrow 10$
90%	9	1	1 $2$ $3$ $4$ $5$ $6$ $7$ $8$ $9$ $10$
100%	10	0	2 $3$ $4$ $5$ $6$ $7$ $8$ $9$ $10$

Cycle modulating the current through the heater has the effect of turning the heater on and off rapidly and therefore, power output is reduced in the long run. Since the switching is zero-cross controlled, the controller knows exactly when power cycles start and finish. Zerocross switching also helps reduce power harmonics that generate unnecessary interference.

The heater current (average current) measured by the controller while cycle modulation is in effect may be approximated as follows:

Heater Current at 100% x Duty Cycle = Average Current

When powerlimit is enabled, a powerlimit current is set by the user. This is essentially the desired average current. The powerlimit control algorithm ensures that the actual current will not exceed the powerlimit setting while optimizing the maximum duty cycle possible. When the average current exceeds the powerlimit setting, the duty cycle is reduce by 10%. When the average current is below the powerlimit setting, the duty cycle is increased by 10%. Before the algorithm increases or decreases the duty cycle, the controller waits until the heater current has reached steady-state at the current duty cycle setting. If the heater is initially off and the controller calls for heat, the duty cycle starts at zero and increases by 10% increments until it reaches a steady-state value. This ramping up effect provides a current-driven softstart whenever the controller calls for heat.

#### **Proportional Control**

Unlike on/off control where the heater is fully on or off, proportional control can partially turn on the heater. The heater output is proportional to the difference between actual temperature and heater setpoint. The relationship is expressed as follows:

(actual temperature – heater setpoint) x k = heater output where k is the proportional gain

To partially turn on the heater, the proportional control function uses cycle modulation in the powerlimit function. By incorporating cycle modulation into the proportional control equation, the algorithm is expressed using the Equation 1.

The deadband factor DB(t) is a time constant that determines the slope of change of the proposed heater on duty cycle with the temperature difference. It is adjusted between 1 to 10 each hour to minimize the difference between the measured temperature and the temperature

$$d(t) = 0 if e(t) \le 0$$
  

$$d(t) = \frac{e(t)}{DB(t)} if 0 < e(t) < DB(t) (1)$$
  

$$d(t) = 1 if e(t) \ge DB(t)$$

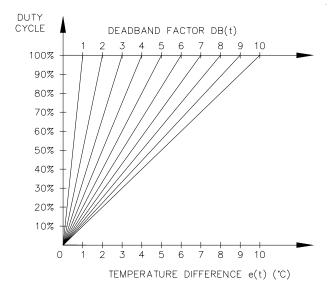
Where a	d(t)	= duty cycle
	DB(t)	= deadband factor (in °C/duty cycle)
-	Ts	= heater setpoint t emperature (°C)
	T(t)	= heater tem perature ( $^{\circ}$ C)
	e(t)	$=Ts-T(t)=\varDelta T (^{\circ}C)$
i	t	= time in seconds

setpoint. Every hour after power up, the controller calculates the absolute values of the temperature differences e(t) and sums them during the hour. Then the total absolute temperature difference is divided by the number of temperature readings taken during the hour. The result is called the Average Absolute Temperature Difference (AATD) for the hour. If current AATD is smaller than the AATD in the previous hour, the deadband factor will be increased or decreased in the same direction. If current AATD is larger than the AATD in the previous hour, the deadband factor will be increased or decreased in the reversed direction. At steady state, the deadband factor used will fluctuate around a optimum value.

Figure 1.3 shows the relationship between the proposed heater on duty cycle and the temperature difference for different deadband factors used.



**Proportional Control** Duty Cycle vs. Temperature Difference



Chapter 1 Product Overview

#### **On/Off Control with Deadband**

The default control mode of the controller is deadband control or simply on/off control with the proportional control setting turned off. On/off control without deadband (that is deadband set to 0 C° or 0 F°; note that these units denote the temperature differential with """ placed to the right of the unit) means that the heater turns on when actual temperature is below setpoint and turns off when above setpoint. However, this causes oscillations when the actual temperature is very close to setpoint. To eliminate oscillations, hysterisis is applied to the on/off control by a deadband value. The on/off control with deadband operation is described by the hysterisis curve in figure 1.4. Assume that actual temperature is well below (setpoint - deadband setting), the controller calls for heat. As the actual temperature rises, the controller continues to call for heat until the actual temperature has reached (setpoint + deadband setting). The controller no longer calls for heat and the heater is off. As the actual temperature cools, the controller does not call for heat until the actual temperature reaches (setpoint - deadband setting). The hysterisis effect is controlled by the momentum of the actual temperature rather than the temperature value itself.

#### Figure 1.4 On/Off Control with Deadband

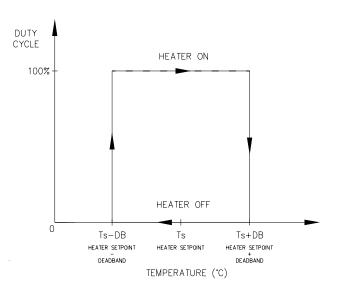
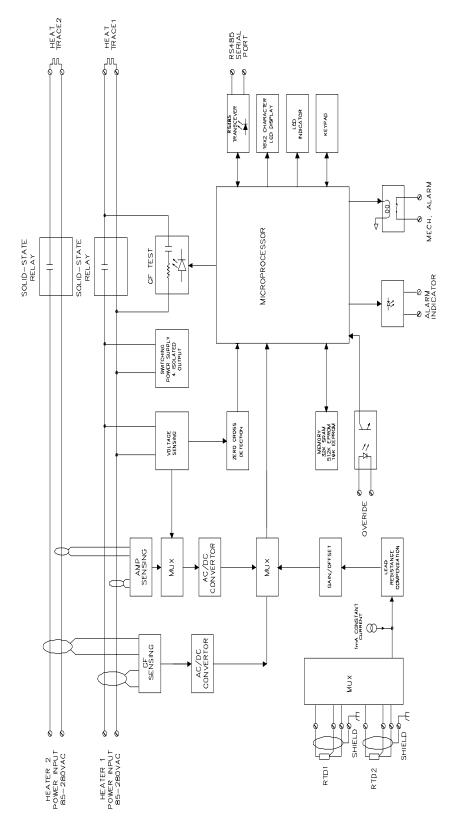


Figure 1.5 Hardware Block Diagram



# **Unpacking the Controller**

Check the shipping cartons for damage, or other signs of rough handling or abuse. If damaged, notify the shipping carrier at once.

Carefully remove the MS-2102 from the shipping box. Save the packing materials in case the unit needs to be transported at a later date.

Inspect face plate for damage and check electronics for loose wiring or damage. Report any damage to the carrier at once.

# **Control Module**

See *Figure 2.1 Main Board Layout* and *Figure 2.2 Power Board Layout* to locate the following:

- S1 Address Enable: When the switch is set to DIS, the Module Number cannot be changed from a master on the data highway. When set to EN, the Module Number can be changed for the next ten minutes from a master on the data highway. During this time the ADDRESS ENABLE light is on.
- S2 Program Enable: When the switch is set to DIS, programming via keypad is disabled; setpoints and configuration cannot be changed. When set to EN, programming is allowed.
- **S3** RS485-120: When the jumper is set to **IN**, the RS-485 line is terminated by a 120 ohm resistor. Only the last Control Module on the data highway should be set to **IN**.

Terminals: Refer to *Figure 2.7* Typical Wiring Diagram, for power, heater and RTD field connections.

- **T 1** Alarm Contact: The mechanical alarm output is rated 30Vdc/100mA, 120Vac/0.52A, 62.5W Max. Without power, the contact is open. With power, it is configurable for normally open or closed.
- **T 2** Alarm Light Output: The output is configurable for normally open, closed or flash. Output is rated 5 Vdc @ 50 mA for an LED type lamp (terminals 18+ and 19-).
- T3 Mater Override Input: Only those heaters which are programmed with Mater Override set to on are affected by the Master Override Input. When the terminals are open, all Master Override Enabled heaters are forced off. When the terminals are closed, all Master Override Enabled heaters are controlled by their individual RTDs unless their Heater Setpoints are set to OFF. In this case, the heaters are turned on. The logic of this input allows either ambient temperature override or load shedding on all or selected heaters. (terminals 24+ and 25-).
- **T4** RTD1 and RTD2 Inputs: 3 wire RTD input. Ground terminal connects to shield or case. Lead resistance compensated. (terminals 6-13).

- **T5** Earth Ground: (terminal 1).
- **T6** Heater 1 Power Input: 85-280Vac/30A max continuous (terminals 2 and 3).
- **T7** Heater 1 Power Output: 85-280Vac/30A max continuous (terminals 4 and 5).
- **T8** Heater 2 Power Input: 85-280Vac/30A max continuous (terminals 26 and 27).
- **T9** Heater 2 Power Output: 85-280Vac/30A max continuous (terminals 28 and 29).
- **T10** Safety Ground: Terminate to ground stud. Termination of safety ground is required for transient protection circuit on RTD inputs and RS485 serial port to operate properly (terminal 14).
- **T11** Extra A/D Inputs/Output: Terminals 22 (POUT) and 23 (PIN1) are the output (+12Vdc) and input (4-20mA dc) connections to the 1<sup>st</sup> 4-20mA analog signal transmitter. Terminals 22 (POUT) and 24 (PIN2) are the output (+12Vdc) and input (4-20mA dc) connections to the 2<sup>nd</sup> 4-20mA analog signal transmitter.

Status Lights:

- L1 Power: Light is on when control power is present.
- L2 Address Enable: Light is on when controller is in Address Enable mode. Light must be on to allow the Module Number to be changed from a master on the data highway.
- L3 Transmit: Flashes when data is being transmitted from the serial port to the data highway.
- L4 Receive: Flashes when data is being received at the serial port from the data highway.
- L5 Override: Light is on when the Override Input terminals are shorted.

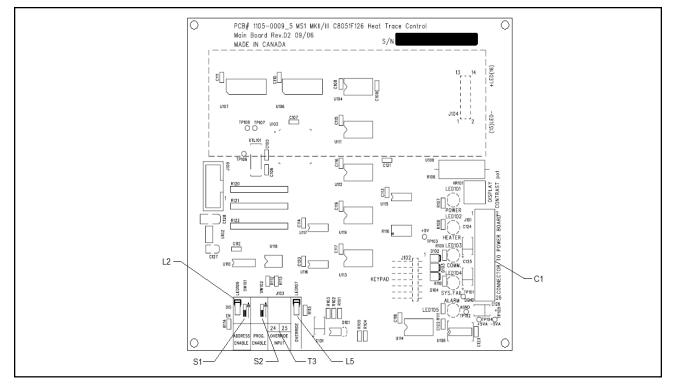
Communication Ports:

- C1 Interface to Main/Power Board: Connector to interconnect power and main board via ribbon cable.
- C2 Serial Port 1: Connection to an RS-485 data highway via a 2-conductor, shielded, twisted pair cable. Maximum Cable length with 32 devices without repeater is 4,000 feet. (terminals 15+, 16-,17 SHD).

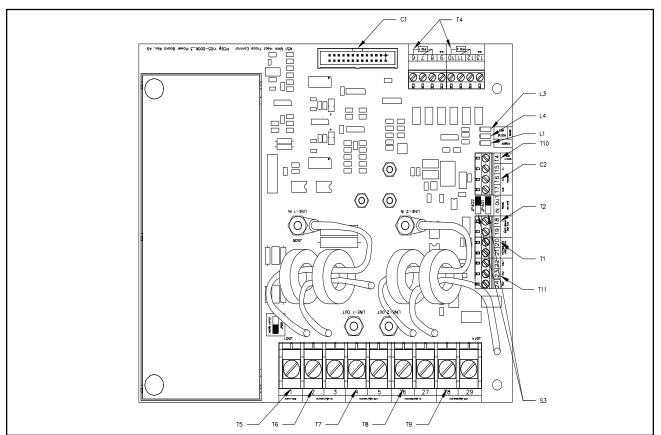


Warning - The ground fault trip function is intended for equipment protection only and should not be used in place of ground fault protection for personnel protection where this is required.

# Figure 2.1 Main Board Layout



# Figure 2.2 Power Board Layout



# Mounting the Controller

Mount the control panel with Unistrut brackets using 1/2" bolts. The Unistrut (or equivalent) mounting allows air circulation to cool the heat-sink. This is important to ensure proper operation of the MS-2102. For optimum readability, mount with the display at eye level and not in direct sunlight. Mounting dimensions are shown in *Figure 2.6*.

# Wire Sizing



Wiring methods should comply with Canadian Electrical or National Electrical Code and local codes. Power and signal wires should not be run in the same conduit system. Wiring should be rated at least 90 °C.

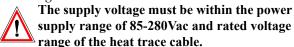
Wire Size (AWG)	Current Load (A)	Max. Ambient Temperature (°C)
6	30	50
8	30	40
10	24	50
12	16	50

# **Conduit and Cabling**

The MS-2102 comes with one 3/4" and three 1/2" conduit knockouts located on the bottom of the enclosure. Conduit hubs should be NEMA-4X rated, such as T&B H050-0.5 and H075-0.75 or Myers equivalent, to maintain a watertight seal. Unused knockouts should be sealed using NEMA-4X rated seals.

# **Power Wiring**

The power input terminals 2 & 3 supply power to both heater 1 and controller, while power input terminals 26 & 27 supply power to heater 2. Size power input wires appropriately to the breaker size and maximum ambient operating temperatures. Maximum breaker size is 30A. Connect power wires to input terminals 2 & 3, and 26 & 27. See *Figure 2.7*.



# **Heater Wiring**

Connect the two heating cables wiring to terminals 4 & 5, and 28 & 29, respectively. See *Figure 2.7*. If the heating cable has a braid, it should be terminated to the ground stud using a ring terminal suitable for #10 stud.



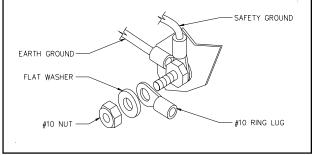
Wiring methods must conform to Class I, Division 2 or Class I, Zone 2 requirements.

# **Ground Connection**

Connect the controller grounding stud directly to a ground bus using the shortest, practical path. Use a tinned copper, braided bonding cable such as Belden 8660. As a guideline, the ground cables should be minimum 96 strands, number 34 AWG each.

The grounding is not only a safety requirement but is necessary for the input transient protectors or the RTD and communication inputs to work properly. The transient protection network is grounded through terminal 14, safety ground, which is bonded to the chassis ground stud. To install the ground connection, remove the outside nut, washer and #10 ring lug provided on the ground stud. Crimp the ground cable onto the ring lug and re-assemble onto the ground stud using the washer and nut.

#### Figure 2.3 Ground Connection



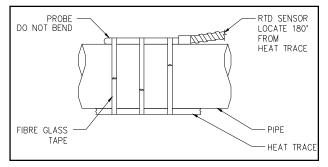
# **RTD Sensor Wiring**

RTD sensors should be 3-wire, 100 ohm, platinum to DIN EN 60751 standard. Mount the RTD element on the pipe, away from the heat trace and 30° to 45° from the bottom of the pipe. The total circuit resistance per conductor from the RTD to the control panel must be less than 10 ohm. Exceeding this resistance will result in a non-linear temperature measurement. Belden cable 8770 or equivalent allows RTDs to be placed up to 1,000 feet from the control panel. Complete all RTD wiring according to *Figure 2.7 Typical Wiring Diagram*.



The RTD probe is delicate and should not be bent or used as a tool to puncture insulation.

Figure 2.4 RTD Mounting



You must install the RTD sensor on the pipe surface or thermal well before the pipe insulation to ensure proper thermal contact. The RTD position should be 180° from the electric heat trace cable which is the coldest spot of the pipe. The RTD sensor may be secured to the pipe by fiber-glass tape. If additional wiring is required for the RTD, shielded 3-lead wire sized 18 or 20AWG must be used for the RTD sensor to minimize the effects of noise pickup. A typical RTD installation is shown in *Figure 2.4*.

# **Communication Wiring**

The MS-2102 is equipped with a communication port that provides continuous monitoring and control from a remote computer, SCADA system or PLC. Communications protocol is Modicon Modbus as discussed in the communications chapter.

Communication is RS-485 mode where data transmission and reception are done over a single twisted pair with transmit and receive data alternating over the same pair of wires.

Shielded twisted pair such as Belden cable 9841 or equivalent is recommended to minimize error from noise. You must observe polarity. For each MS-2102 controller, you must connect A+ terminals together and B- terminals together. The shield terminal (labelled SHD) connect to shield wire of the cable.

To avoid loop currents, the shield should be grounded at one point only. Connect between controllers in daisychain fashion. The total length of this daisy-chain should not exceed 4,000 feet. The maximum number of devices connected is 32 to avoid exceeding driver capability. You can use commercially available repeaters to increase the number of devices over 32. Avoid star or stub connections.

Terminate the first and last device in the daisy-chain loop. Each controller is equipped with a termination jumper as shown in *Figure 2.2*.

The controller comes unterminated from the factory (JP401 and JP402 in **OUT** position). If the controller is the first or last device, it can be terminated by moving the two jumpers (JP401 and JP402) to the **IN** position. The communication port is powered by an isolated power supply with opto-coupled data interface to eliminate noise coupling. In addition, surge protection devices are employed at the front end of the port to protect against lightening strikes and ground surge currents. These may cause large, momentary voltage differences between devices on the data highway.

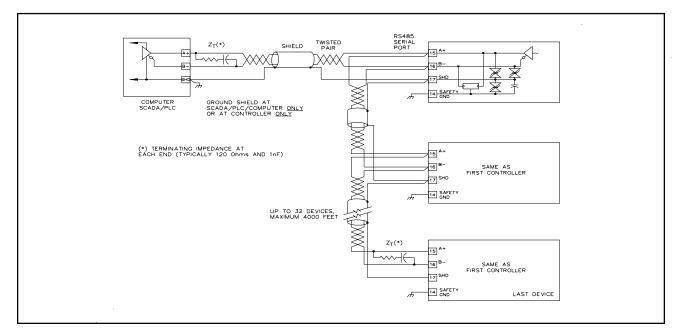
# Alarm Wiring

The MS-2102 has one passive (mechanical) alarm contact and one active alarm output for driving an LED alarm indicator. Without power, the alarm contact is open. With power, it is software configurable for normally open or closed. The alarm LED output is software configurable for alarm on, alarm off or flash during alarm. Refer to *Figure* 2.7 for alarm output terminals.

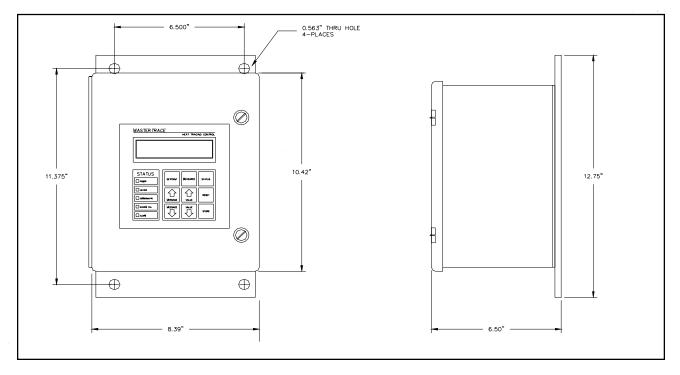
The mechanical (dry) alarm output is rated 30Vdc/100mA, 120Vac/0.52A, 62.5W Max.

The alarm LED output is rated 5Vdc, 50mA. It can drive a 6Vdc LED indicator. Alarm output is designed for interface to annunciator, panels, PLC or DCS.

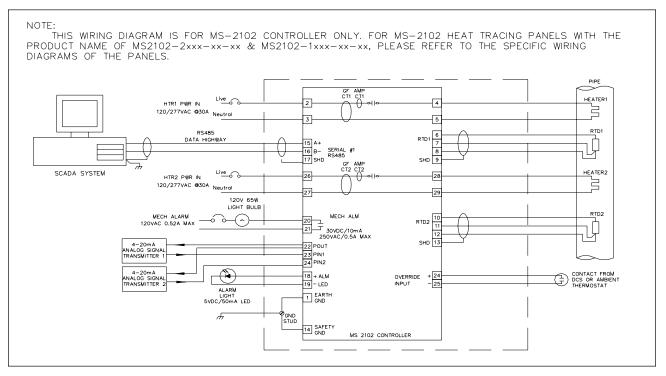
Figure 2.5 Communication Wiring



# Figure 2.6 Mounting Dimensions



# Figure 2.7 Typical Wiring Diagram



Warning - Explosion Hazard - Substitution of components may impair suitability for Class 1, Division 2 or Class 1, Zone 2.



Warning - Explosion Hazard - Do not disconnect equipment unless power has been switched off or the area is known to be non-hazardous.

# Introduction

The MS-2102 has many features that provide trouble-free operation of heat tracing installations.

An example is presented to illustrate MS-2102 setup and operation on a specific installation. MS-2102 is easy to program and setting up a unit to your specific requirements should be straight forward.

Example: Heater 1-2 will be programmed as: **Configuration** 

1) The module number is 1 and the heater 2 of this module is used to control a heavy feed line.

- 2) Mineral insulated (MI) cable is used for the heater.
- 3) Normally open alarm contact to remote programmable control
- 4) Northern climate installation outdoors.
- Operating temperatures: -40~50 °C (LCD: -20~50 °C) NEMA-4X weatherproof enclosure.

Setpoint	Required	Range		
Fluid maintain temperature	50 C	-50 to 500 F/off /none		
Low temperature alarm	35 C	-50 to 500 C/off		
High temperature alarm	no alarm	-50 to 500 C/off		
Nominal heater current	5 amps	0.0 to 30.0A		
Nominal heater voltage	115 VAC	100 to 300 Vac		
Ground fault trip current	30 mA	10 to 1000mA /off		
Ground fault alarm current	20 mA	10 to 1000mA /off		
System exercise time interval	8 hours	1-24/off		
Cost per Kilowatt hour	\$0.06	\$0.01-\$0.50		
Heater name	HEAVY OIL LINE	16 characters		
Install and commission the control in the following order:				

STEP 1: Selecting the heater STEP 2: Enabling the heater

STEP 3: Entering setpoints

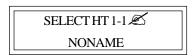
STEP 4: Testing heater and alarms

STEP 5: Monitoring system status

## Selecting the Heater

To select the heater circuit,

- 1. Press [SETPOINTS] once to access the Setpoints Operating Values group of messages.
- 2. Press [MESSAGE ♣] until the following message appears:



- 3. Within the message "SELECT HT M-N", M is the module number and N is the heater circuit number within the control module.
- 4. Press [VALUE ↓] key to have "SELECT HT 1-2" displayed.
- 5. Press [STORE] key to select the heater 1-2.

# **Enabling the Heater**

To enable the heater circuit,

- 1. Press [SETPOINTS] once to access the Setpoints Operating Values group of messages.
- 2. Press [MESSAGE ♣] until the following message appears:



- 3. Press [VALUE ] or [VALUE  $\clubsuit$ ] keys to toggle Heater Enabled between **YES** and **NO**.
- 4. When **YES** is displayed, press [STORE]. Enabling the Heater

# **Entering Setpoints**

<u>Accessing the Program</u>: Since the heater control display and keypad are normally accessible to passers-by who may wish to read measured values, a program disable feature is used to prevent accidental changes to the setpoints. So before any setpoints can be entered, the PROGRAM ENABLE dip switch (located on the bottom of the board behind the enclosure door) must be set in the ENABLE position.

When programming is complete, set the PROGRAM ENABLE dip switch to **DISABLE** to prevent accidental changes to the setpoint.

If you try to store a setpoint without the dip switch in the **ENABLE** setting, the setpoint will not be saved and this message will flash on the screen:



Now that the MS-2102 control is ready for programming. For further information about the organization of all the messages or for details on the range and application of each message see *Chapter 6 Setpoint Values*. It is not necessary to enter setpoints in any particular order and any setpoint can be changed later.

<u>Entering Temperature Units °C/°F:</u> Temperature values can be displayed in degrees Celsius or Fahrenheit. To enter values in preferred units, enter this selection first.

To enter temperature units,

1. Press [SETPOINTS] 3 times for System Setup mode and [MESSAGE ♣] key until the following message is displayed:



- 2. Press [VALUE ] or [VALUE ♣] to toggle selection between Celsius and Fahrenheit.
- 3. When Celsisus is displayed press [STORE]. A brief message appears:



Then the message reverts back to the previously entered value for verification. If instead you get the message:



the PROGRAM ENABLE dip switch has not been set to the ENABLE setting. This must be done to proceed with setpoint programming.

Assuming the setpoint was stored, all values will be displayed in °C. Temperature values can automatically be converted to °F at any time by selecting Fahrenheit using this message.

TEMPERATURE	-
UNITS: Celsius	

<u>ASSIGNING HEATER NAME:</u> To assist operators in troubleshooting, you can program each heater in the MS-2102 control with a heater name. You can assign up to 16 characters to the name of a heater.

To assign a heater name,

- 1.Press [SETPOINTS] twice to enter the Heater Setup group of setpoints.
- 2. Press the [MESSAGE ♣] key until the heater name message appears:



Note: The heater default name when MS-2102 is shipped from the factory is "NONAME". You can program each letter separately with upper and lower case characters, numbers, space or the special symbols !@#\$%^&\*()?.,":;}]{[. Uppercase characters are generally more legible. For this example the name has arbitrarily been chosen as:

# HEAVY OIL LINE

(The cursor appears under the first letter  $\underline{N}$  in "NONAME").

- 3. Press and hold down [VALUE ] or [VALUE ♣] until the desired letter you want appears above the cursor, then press [STORE].
- 4. Press [STORE] to save the current letter displayed and advance the cursor to the next letter.

For Example:

- H: Press [VALUE ] or [VALUE  $\oplus$ ] until Happears. Press [STORE]. The letter H now appears in the first character position and the cursor is under the second character.
- E: Press [VALUE ♣] until E appears. Press the [STORE]. The first 2 letters are now HE and the cursor is under character position 3.



- 5. Continue entering each letter this way until the complete new name is displayed.
- 6. With the cursor under the last character position at the right edge of the message screen (blank character), press [STORE] until the cursor is at the end of the line. A brief message will flash:



followed by the new name that has been stored:

	_
HTR 1-2 NAME:	
HEAVYOILLINE	

The new heater name is now saved in non-volatile memory and will remain until you change it.

If a character is accidentally entered incorrectly,

1. Either press [RESET] to start over, or

go to the end of the line to save the displayed message with the error.

- 2. Press [MESSAGE ] or [MESSAGE  $\clubsuit$ ] to exit and return to the 1<sup>st</sup> character position.
- 3. Press [STORE] until the cursor is under the incorrect character. Proceed as before until new letters are entered.
- 4. Press [STORE] to skip over the correct letters until on the last character position.
- 5. Press [STORE] to save the corrected message.

You can now enter setpoint information for the system configuration and data for the heater. Turn to *Chapter 6 Setpoint Values*. Read the first few pages to see how the messages are organized and get a summary of all setpoints. Skip the latter part of this chapter which gives a detailed description of each message.

#### ENTERING SETPOINT TEMPERATURE:

Set the desired maintained temperature for the fluid in the pipe being traced by this heater temperature setpoint.

To enter the heater setpoint,

1. Press [SETPOINT] once to display this message::



- 2. Press and hold [VALUE ] until 50°C is displayed. If you pass the required value, use [VALUE ♣] to decrease the number displayed.
- 3. Press [STORE] to save the new value. When a new value is successfully stored a brief acknowledgement message will flash on the screen:

SETPOINT
STORED

In this example, the temperature at which the control will turn on and supply full system voltage to the

heater is now set to 50 °C.

- 4. Press [MESSAGE ♣] after each setpoint to access the next setpoint.
- 5. Hold [VALUE û] down until the word OFF appears to defeat any setpoint not required. For example, if a high current alarm is not required, set the value to off. A detailed description of each message is found in *Chapter 6 Setpoint Values*.

# **Testing Heater & Alarms**

You can force heater and alarm outputs on using the test mode. Like setpoints, this mode requires that the PRO-GRAM ENABLE dip switch be set to ENABLE or when you try to store a test value a message will flash:



Testing a Heater:

To test operation of a heater, it can temporarily be forced on.

- 1. Press [SETPOINT] 4 times.
- 2. Press [MESSAGE  $\mathbb{P}$ ] until the message appears:

HEATER TEST	
DISABLED?	

3. Press and hold [VALUE û] or [VALUE ↓] to set the ON time in hours. The range is DISABLED/1-24 hours/ON-CONTINUOUSLY. For example, to turn on the heater for one hour, press [VALUE む] to display '1 hour' then press [STORE]. The heater will be energized no matter what the heater temperature setpoint is unless there is a ground fault trip. After the selected time period the heater will automatically go off. While the heater is on, the front panel HEATER ON indicator will be illuminated. To override the test mode, press [VALUE ♣] until **DISABLE** appears and then store this value. Holding the [VALUE ①] key until the word ON CONTINUOUSLY appears leaves the heater always energized until the MS-2102 controller is manually powered off or until this setpoint is set to **DISABLE**. Consequently, selecting a value of **ON CONTINUOUSLY** should be used with caution since it overrides normal control operation and could lead to excessive heating or waste power if accidentally left on. A warning message appears in the status mode (press status key to enter status mode) whenever a heater or alarm is forced on.

- 4. Press [STORE] to save the value.
- 5. With the heater forced on, verify that the expected current is flowing using the actual current message, located in ACTUAL\OPERATING VALUES\HEATER CURRENT. You can use a clamp-on ammeter attached to one of the heater wires to compare readings. With proportional control selected, the readings may differ due to harmonics in the current waveform.

<u>Testing Alarms:</u> The manual alarm setpoint works exactly like the manual heaters setpoint except that it energizes the output alarm and indicator. This setpoint is useful for commissioning a new system or checking alarm circuits. Normally this setpoint will be DISABLED.

# **Monitoring System Status**

Now that the MS-2102 controller has been programmed for a specific application, you can check system status. If no keys are pressed for the time specified in DISPLAY TIMEOUT message located in SETPOINT\SYSTEM SETUP\DISPLAY TIMEOUT, the display will automatically go into the default message mode. **System Status** mode is recommended; that is, the display will automatically display all alarms. If desired, you can change this to a specific message later by reprogramming the default message.

Access actual values by pressing [MEASURED]. These are divided into 2 groups. Pressing [MEASURED] once accesses the group of messages that show current values of temperature, current, etc. Pressing [MEASURED] twice displays the statistics data such as minimum/ maximum temperature, power consumption, running hours etc. Unlike setpoints, you cannot change actual values using [VALUE  $\hat{T}$ ], [VALUE  $\hat{T}$ ] or [STORE].

There is a summary of all Measured Values messages at the beginning of *Chapter 5 Measured Values*. To view the actual values,

- 1. Press [MEASURED].
- 2. Press [MESSAGE  $\clubsuit$ ] to view each actual value.
- 3. Continue examining each value of interest by pressing the [MESSAGE ♣] key and referring to *Chapter 5 Actual Values*.

Monitoring Heater Temperature To monitor the heater temperature, 1. Press [MEASURED] once to display:



This is the temperature value that the controller will use with the heater setpoint to determine the heater output. The 2 heaters in MS-2102 use the actual temperatures of RTD1 & RTD2 as their control temperatures, respectively. If no RTD sensor is connected or a lead is broken the value **RTD OPEN** appears. This is an alarm condition.

When the temperature falls below the heater setpoint, 50  $^{\circ}$ C in our example, heater 2 in the MS2102 switches on to supply power to the heater circuit. It stays on until the temperature rises above the heater setpoint (50  $^{\circ}$ C). Once the system has been running for a few hours, the heater temperature should be at or above this setpoint value.

If hot fluid is being pumped through the pipe, the measured temperature may be much higher than the setpoint temperature. But in this case, no power should be supplied to the heater and the **HEATER ON** indicator will be off.

If the heater temperature is less than the minimum display value (-50 °C/-58 °F), the word **RTD SHORT** appears. If the temperature is over the maximum value (+ 500 °C/932 °F), the word **RTD OPEN** appears. If an abnormal value appears, particularly on a new installation, check that the correct RTD sensor type has been installed (100 OHM platinum DIN EN 60751) and that the three RTD wires are wired to the correct terminals.

Monitoring Actual Current:

To monitor the actual current,

- 1. Press [MEASURED].
- 2. Press [MESSAGE ♣] 5 times to display:



This value is the actual measured current of the heater. Resolution is to 0.1 amp over a range of 0.0 to 30.0 amps. Above 30.0 amps the value displayed reads O.L (Overload).

With MI (Mineral Insulated) cable used in this example, it will either be 0.0 if the heater is not energized or a fairly constant current such as 5.0 amps.

Monitoring Ground Fault Current:

Some stray current always flows to ground due to capacitance effects and leakage.

To monitor ground fault current,

1. Press the [MESSAGE  $\mathbb{Q}$ ] key from the heater voltage message

Press [MEASURED] then [MESSAGE <sup>(1)</sup>] 6 times to display:

GROUND FAULT	
CURRENT: 15 mA	

In this example, any value above 20 mA would cause an alarm and if a ground fault current above 30 mA were detected, MS-2102 would remove power to the heater. If the heater is off, the value displayed would be 0. For values over 15 mA, check the system for insulation leakage problems.

You have now checked all actual values.

<u>Viewing Statistical Data:</u> In addition to actual values that are present, such as current and temperature, the MS-2102 continuously gathers and computes historic information about the heat tracing system to determine cost of operation, utilization, trends etc. This can be quite useful in spotting potential problems or in designing similar systems for other applications. Data is saved indefinitely but you can be clear it anytime.

To view statistical data,

1. Press [MESSAGE ♣] from the actual value messages just displayed to take you to the statistics values group or

Press [MEASURED] twice to display the first message in this group. Either way displays a brief message to indicate the start of the statistics page followed by the first value message:



Since this is a new installation any random data should be cleared.

2. Press [MESSAGE ♣] in this group until the message appears:



3. Reset statistics for a new measurement interval. The MS-2102 keeps track of when the measurement interval started. See *Chapter 5 Measured Values* for a complete description of how data is gathered and application ideas.

This completes setpoint programming and system testing.

Set the PROGRAM ENABLE dip switch to DISABLE to prevent accidental setpoint changes or tampering. By following this procedure, it should be fairly easy to install a similar control application. More details about each message is provided in *Chapter 5* and *Chapter 6*.

As you use the system, some setpoints may need adjusting. For example, frequent low temperature alarms might indicate that the setpoint value was set too close to normal heater temperature swings and needs to be lowered. Once the system has been operating normally for a while an alarm will indicate a change that needs investigation.

The flexibility and many features of the MS-2102 system significantly reduces problems caused by heat tracing malfunctions.

# Overview

The front panel provides the local operator with LCD alphanumeric display and keypad. The display and status indicators update alarm and status information automatically. The keypad is used to select the appropriate message for entering setpoints or displaying Measured Values.

The 32 character, backlit, LCD display provides English messages that are visible under various lighting conditions. When the display and keypad are not being used, the screen displays system information, which is definable through three user selected default messages. These default messages only appear after a user defined period of inactivity. Press either [SETPOINT], [MEASURED] or [STATUS] to override the default messages.

# **Operating the Keypad**

The MS-2102 display messages are organized into pages under headings **Setpoints** and **Measured** Values.

[SETPOINT]: Provides entry to the Setpoint Menu which allows you to navigate through user settable parameters. See *Chapter 6 Setpoint Values* for detailed messages.

[MEASURED]: Provides entry to the Measured Values Menu which you to navigate through measured parameters.

- [STATUS]: Provides immediate access to the System Status Menu which displays the alarm status for the Controller and allows access to individual alarm details.
- [MESSAGE ①]: Allows you to move up through the selected menu.
- [MESSAGE  $\[Delta]$ ]: Allows you to move down through the selected menu.
- [VALUE ①]: Allows you to increase the value of the displayed selected item.
- [STORE]: Allows you to save the changed value of the selected item.
- [RESET]: Allows you to clear alarms that are no longer active.

# **Status Lights**

Refer to Figure 4.1 Display, Front View.

- L10 Power: The green Power light should be on at all times indicating that control power is applied to the Module. If the light is off, either there is no control power or the display has a malfunction and requires servicing.
- L11Heater: The green **Heater** light is on if the heater is energized.
- L12 Communicate: Random flashing of the green Communicate light indicates that serial communications are active on the controller..
- L13 System Fail: The red System Fail light should be off, indicating that the system check was successful.
- L14 Alarm: The red Alarm light is off when there are no alarms. The light flashes if any alarm conditions are present. Press [STATUS] to view alarms.

# Alphanumeric Display

Refer to Figure 4.1 Display, Front View.

• **D10** Display: Two lines with 16 alphanumeric characters per line. It is backlit for viewing in low-light conditions.

# Keypad

Refer to Figure 4.1 Display, Front View.

• **K10** Display Keypad: Consists of nine keys which, when used in connection with the Alphanumeric Display, allow complete control of programming and monitoring of the Control Module.

# **Display Contrast**

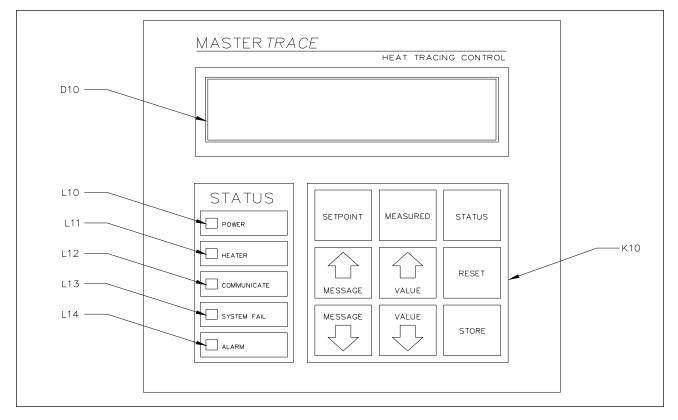
Refer to Figure 4.2 Contrast Control.

• **P1** LCD display: After the MS-2102 is field mounted, it may be necessary to adjust the display contrast to compensate for the viewing angle. To adjust the contrast, open the enclosure door and locate the potentiometer (labelled **DISPLAY CONTRAST** pot) on the board attached to the enclosure door. Turn the set-screw clockwise or counter-clockwise until the display is desirable.

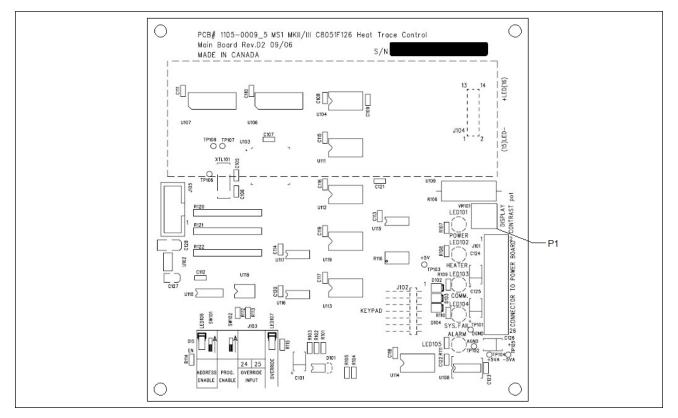
# **Heater Numbering**

Each heater is identified by a number of the form "M-N", where "M" is the Module Number and N is the heater circuit number within the control module. Each Control Module on the same data highway must have a unique Module Number.

# Figure 4.1 Display, Front View

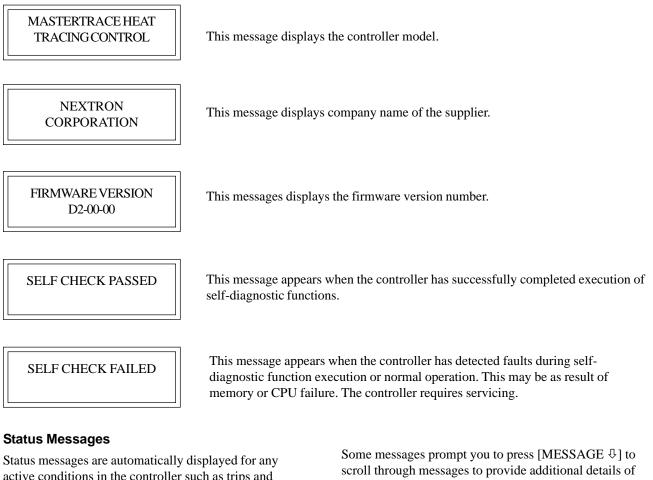


# Figure 4.2 Contrast Control



# Startup Messages

Startup messages are displayed when power is applied to the controller.



active conditions in the controller such as trips and alarms. These messages provide an indication of the current state of the controller.

the controller status.

SYSTEM OK NO ALARMS

\*\*2 ALARMS\*\* PRESS MESSAGE DOWN

PRESS MESSAGE DOWN FOR NEXT ALARM

This message indicates there are no alarms present.

This message indicates the number of alarms on the controller. Press [MESSAGE  $\mathbb{Q}$ ] to locate the problem and the cause.

This message marks the end of details to an alarm. Pressing [MESSAGE  $\mathbb{Q}$ ] to scroll through details of the next alarm.

NO MORE ALARMS

This message appears when the user has scrolled through all alarms.

# **Flash Messages**

Flash messages are warnings, errors or general information displayed in response to a key press. The duration of the message can be configured in SETPOINTS\SYSTEM SETUP\SCAN TIME. The factory default is three seconds.

SETPOINT STORED

This message appears when a setpoint has been stored.

PRESET DISABLED ALARM ACTIVE This message indicates that the alarm cannot be reset because the alarm condition is still present.

NAME STORED

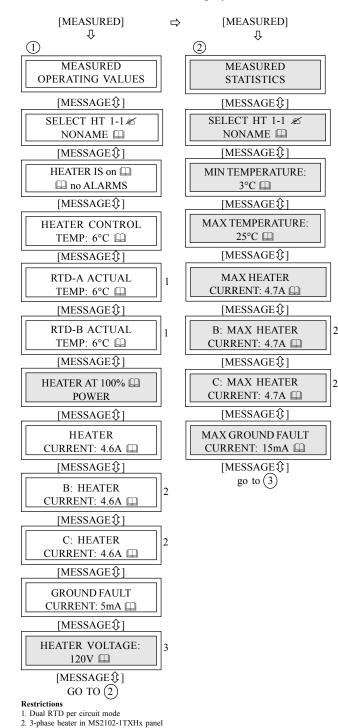
This message appears when the heater name has been stored.

NOT STORED PROG DISABLED This message indicates that the program enable dip switch or program access function is set to disable and programming is not allowed. Refer to *Chapter 6, Section 6.3,* for details on Setpoint Access Security.

# Overview

Access values and statistics in the Measured Values mode. The messages are organized into groups for easy reference as shown below. Throughout this chapter each group is detailed by section.

[MEASURED] provides access to the Measured Values Menu which allows the user to display the Measured Values of the selected heater in the control module. The Measured Values Menu is arranged in two groups. Pressing [MEASURED] twice quickly access the top of the second group. [MESSAGE  $\hat{T}$ ] allows you to move up through the selected menu. [MESSAGE  $\hat{T}$ ] allows you to move down through the selected menu.



HTR SET VOLTAGE is set to measured. Advanced User Mode



Û

go to (1)

# Operating

MEASURED: OPERATING VALUES	MESSAGE NO: DEFAULT VALUE DISPLAY MODE:		APPLIES TO: VALUE RANGE: RESTRICTIONS	
SELECT HT M-1 & NONAME	Number in a form o is the heater circuit	All s the heater cin f M-N. M is the within the Cont DRE] to select	e Module Number o rol Module. Press [ a heater circuit. For	
HEATER IS ON COMPARISON IN NO ALARMS	heater circuit is on o	All e is the status of or off and the r s forced on by I	number of alarm me	Selected Heater on, off, man on, no: 1 to 9 alarms None er. It indicates whether the essages associated with the ction if <b>man on</b> is displayed.
HEATER CONTROL TEMP: 6°C	of the selected heate comparing the Heat	All s the displayed er's RTD. MS- er Control Ten	value based on the 2102 controls the se operature to the Hea	Selected Heater -50 to 500 °C, RTD Open -58 to 932 °F, RTD Fault Heater Setpoint must not be <b>off</b> or <b>none</b> . actual measured temperature elected heater circuit by ter Setpoint. If the tempera- <b>TD SHORT</b> is displayed.
RTD-AACTUAL TEMP: 6°C	heater circuit. It is u	All e is the actual r ised to calculat temperature is	neasured temperatu te the Heater Contro	Selected Heater -50 to 500 °C, RTD A Open -58 to 932 °F, RTD A Fault Dual RTD per circuit mode re of RTD-A sensor for the ol Temperature based oo the nge, then <b>RTD A OPEN</b> or
RTD-BACTUAL TEMP: 6°C	MESSAGE NO: DEFAULT VALUE: DISPLAY MODE: The displayed value heater circuit. It is u	M1-06 N/A All e is the actual r ised to calculat temperature is	neasured temperatu te the Heater Contro	Selected Heater -50 to 500 °C, RTD B Open -58 to 932 °F, RTD B Fault Dual RTD per circuit mode re of RTD-B sensor for the ol Temperature based oo the nge, then <b>RTD B OPEN</b> or

HEATER AT 100% 🛄 POWER	with PROPORTION	Advanced e is the percent IAL CONTRO that the circui	L and/or POWERLI t is energized for 3	Selected Heater 0 to 100% None he heater circuit. For example, IMIT on, a percentage duty out of 10 power cycles. For
HEATER CURRENT: 4.6A	the heater is off, this	All s is the actual of s value is zero. of PROPORT	If the current exceed IONAL CONTROL	Selected Heater 0 to 30.0/100.0 A, O.L. None rent of the heater circuit. If eds the value range, then <b>O.L.</b> or POWERLIMIT functions
B: HEATER CURRENT: 4.6A	is off, this value is z	All is the actual pero. If the curr f PROPORTIC	bhase-B current of t rent exceeds the value NAL CONTROL o	Selected Heater 0 to 100.0 A, O.L. MS2102-1TXHx panel he heater circuit. If the heater ue range, then <b>O.L.</b> is r POWERLIMIT functions
C: HEATER CURRENT: 4.6A	is off, this value is z	All is the actual pero. If the curr f PROPORTIC	bhase-C current of t rent exceeds the value NAL CONTROL o	Selected Heater 0 to 100.0 A, O.L. MS2102-1TXHx panel he heater circuit. If the heater ue range, then <b>O.L.</b> is r POWERLIMIT functions
GROUND FAULT CURRENT: 15mA	MESSAGE NO: DEFAULT VALUE: DISPLAY MODE: The displayed value exceeds the value ra	All e is the ground		Selected Heater 0, 10 to 1000 mA,O.L. None fault current. If the current
HEATER VOLTAGE 120V	Control Module. If MS2102 controller, when Selected Heat be the voltage of the feeding to terminal	All e is the measur the voltage exc this voltage is er is selected t e first heater ci 2 & 3 on the C oltage in statis	RESTRICTIONS: ed supply voltage a ceeds the value rang always the voltage o heater 2. For MS2 rcuit if heater 1's po ontrol Module. Thi stics calculation for	Selected Heater 85 to 300 V, O.L. HTR SET VOLTAGE is set to <i>measured</i> . cross treminal 2 & 3 on the ge, then <b>O.L.</b> is displayed. For of the first heater circuit even 2102 panels, this voltage may ower-in voltage is also s voltage is displayed and the selected heater when

atistics				
MEASURED: STATISTICS 🕮	MESSAGE NO: DEFAULT VALUE: DISPLAY MODE:	M2-13 N/A Advanced	APPLIES TO: VALUERANGE: RESTRICTIONS:	Control Module N/A None
SELECT HT M-1 ≠ NONAME	Number in a form o	All s the heater ci f M-N. M is th	e Module Number o	ircuit has a unique Heater of the Control Module and N
		ORE] to select	a heater circuit. Fo	VALUE û] or [VALUE ↓] r convenience and to reduce
MIN TEMPERATURE: 3°C 📖	MESSAGE NO: DEFAULT VALUE:	M2-15 N/A	APPLIES TO: VALUE RANGE:	Selected Heater -50 to 500 °C -58 to 932 °F, RTD Short
	displayed value is <b>F</b>	RTD Short, a v	Measured Tempera value less than the m	Heater Setpoint is not off. ature since the last reset. If the ninimum range was recorded with all statistics, use RESE
MAX TEMPERATURE: 25°C 📖	MESSAGE NO: DEFAULT VALUE:	M2-16 N/A	APPLIES TO: VALUE RANGE:	Selected Heater -50 to 500 °C -58 to 932 °F, RTD Open
]	the displayed value	is <b>RTD OPEN</b> he displayed v	t Measured Temper I, a value greater tha	Heater Setpoint is not <b>off</b> . rature since the last reset. If an the maximum range was []. To reset with all statistics,
MAX HEATER CURRENT: 4.7A	the displayed value	is <b>O.L.</b> , a valu	e greater than the m	Selected Heater 0.1 to 30.0/100.0 A, O.L. None irrent since the last reset. If naximum range was recorded with all statistics, use RESE
B: MAX HEATER CURRENT: 4.7A	MESSAGE NO: DEFAULT VALUE: DISPLAY MODE: The displayed value the displayed value	is <b>O.L.</b> , a valu	e greater than the m	Selected Heater 0.1 to 100.0 A, O.L. None rrent since the last reset. If naximum range was recorded with all statistics, use RESE
C: MAX HEATER CURRENT: 4.7A	the displayed value	is <b>O.L.</b> , a valu	e greater than the m	Selected Heater 0.1 to 100.0 A, O.L. None rrent since the last reset. If naximum range was recorded with all statistics, use RESE

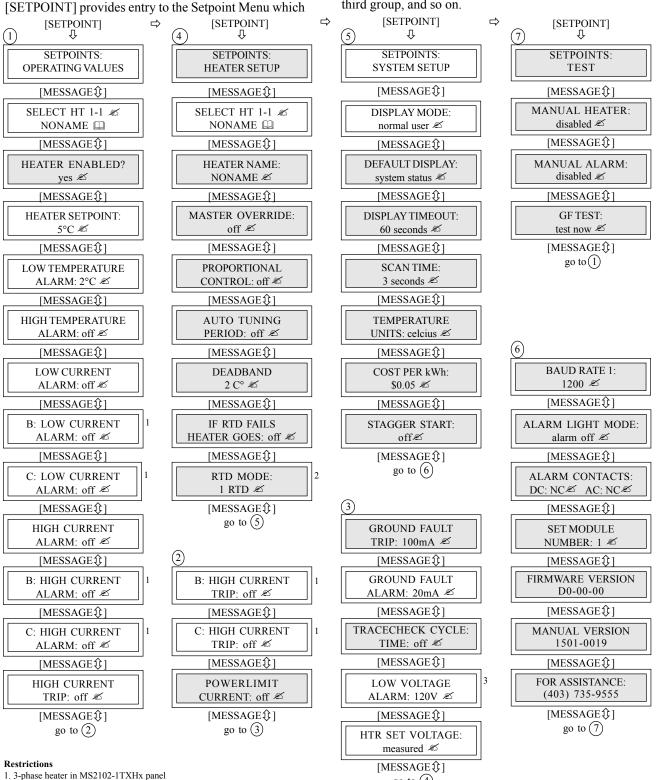
MAX GROUND FAULT CURRENT: 15mA	displayed value is (	Advanced e is the highest <b>D.L.</b> , a value g	reater than the max	Selected Heater 0, 10 to 1000 mA,O.L. None rent since the last reset. If the imum range was recorded. To ith all statistics, use RESET
ENERGY USED LAST DAY: 42.2kWh	Heater Current time	Advanced e is the energy s the Heater Vo	ltage/HTR SET VC	Selected Heater 0 to 1000 MWh None hergy is calculated from the DLTAGE integrated over time. burs. It cannot be reset.
TOTAL ENERGY USED: 42.2kWh	from the Heater Cur	Advanced e is the energy rent times the I played value is	Heater Voltage/HTR O.L., a value great	Selected Heater 0 to 1000 MWh None reset. Energy is calculated SET VOLTAGE integrated er than the maximum range
ENERGY COST LAST DAY: \$33.92		Advanced e is the energy ed times the Co	OST PER kWh. Thi	Selected Heater \$0 to \$100,000.00 None 7. Energy cost is calculated is value is automatically
TOTALENERGY COST: \$33.92		Advanced e is the energy		Selected Heater \$0 to \$100,000.00 None reset. Energy cost is & kWh. To reset, use RESET
TOTAL RUN TIME 20966 hrs 🛄	MESSAGE NO: DEFAULT VALUE: DISPLAY MODE: The displayed value Module. It is useful	Advanced e is the total tir		s first applied to the Control
HEATER ON TIME 80 hrs 🕮	1 5	Advanced e is the accum It indicates ho	w active the heater	heater circuit has been on circuit is and can be useful

HEATER IS ON	since the last reset. P RESET x 100%. It i maintenance. Interp	Advanced e is the percen PERCENT ON ndicates how a pretation of thi n indication of	TIME = HEATER C active the heater circ is value depends on	Selected Heater 0 to 100% None e heater circuit has been on DN TIME ÷ TIME SINCE cuit is and can be useful for the process but large heater or the insulation. To
TIME SINCE RESET 48 hrs 🕮	MESSAGE NO: DEFAULT VALUE: DISPLAY MODE: The displayed value reset by factory rese	Advanced e is the total tin		
RESET STATISTICS? no Ø		Advanced all the statisti		Selected Heater yes, no None otal Run Time/Time Since ergy Cost Last Day/Total
ARE YOU SURE? no <i>Æ</i>	Energy Cost for the	e <b>selected hea</b> n your request	ter. Select yes and t Again, select yes a	then press [STORE]. You nd then press [STORE].

## **Overview**

The MS-2102 has a considerable number of programming setpoints for flexibility. Setpoint messages are organized into groups for easy reference as shown below. Throughout this chapter each group is detailed by section.

allows you to program and test the Control Module. The Setpoint Menu is arranged in four groups. Pressing [SETPOINT] twice quickly to access the top of the second group; press three times to access the top of the third group, and so on.



2. Dual RTD per circuit mode

3. HTR SET VOLTAGE is set to measured.

Advanced User Mode

go to (4)

# **Setpoints Entering**

Prior to operating the heat trace, you must enter process setpoints, alarm levels and alarm output configuration via front panel keypad and display, RS485 port or SCADA system running user written software.

The MS-2102 leaves the factory with default setpoint values shown in the message details. You can leave many of the factory default settings unchanged.



Warning: As a minimum, enter setpoints in the operating values group (S1) to ensure proper operation of the heat trace.

# Operating

# **Setpoint Access Security**

The setpoint access security is achieved via the Program Enable Dip Switch. You can program setpoints through the keypad by setting the program enable dip switch to the **ENABLE** position. Access the dip switch by opening the enclosure door and locating the switch at the bottom of the board on the enclosure door. When setpoint programming is complete, renturn the dip switch to the disable position. Disabling program enable does not restrict setpoint access through the communciations.

SETPOINTS: OPERATING VALUES	MESSAGE NO: DEFAULT VALUE DISPLAY MODE:	S1-01 : N/A All	APPLIES TO: VALUE RANGE: RESTRICTIONS:	
SELECT HT M-1 & NONAME	in a form of M-N. M circuit within the C	l is the Module ontrol Module. a heater circuit	Number of the Con Press [VALUE 飰]	
HEATER ENABLED? yes 🗷				Selected Heater yes, no None eater circuit. You cannot access ater is enabled. Select <b>no</b> if the
HEATER SETPOINT: 150°C Z	if the Heater Contro The circuit is de-en Heater Setpoint plu POWER LIMIT fu <b>none</b> , then the heater	68 °F All e maintain tem of Temperature nergised if the s the deadband nctions affect er circuit is on	RESTRICTIONS perature. For on-off is less than the Hea Heater Control Te Both the PROPOF heater switching. I and has temperature	Selected Heater -50 to 500 °C, none, off -58 to 932 °F, none, off : None control, the circuit is energised ter Setpoint less the deadband. emperature is greater than the RTIONAL CONTROL and the f the Heater Setpoint is set to e monitoring with no tempera- e heater circuit is on and has no

temperature monitoring or control.

LOW TEMPERATURE ALARM: 120°C Z	MESSAGE NO:S1-05APPLIES TODEFAULT VALUE: $5^{\circ}$ CVALUERAN $41^{\circ}$ FDISPLAY MODE:AllRESTRICTIONRESTRICTIONThis function sets the Low Temperature AlarmHeater Setpoint.To disable this alarm, set the v.Temperature is less than or equal to this setpoactivated and a LOW TEMPERATURE ALAAStatus messages.The alarm deactivates when the setpoint.	<ul> <li>NGE: -50 to 500 °C, off -58 to 932 °F, off</li> <li>ONS: Heater Setpoint must not be off.</li> <li>m setpoint. <i>It must be less than the</i> alue to off. When the Heater Control bint, the Low Temperature Alarm is</li> <li>RM message is added to the System</li> </ul>
HIGH TEMPERATURE ALARM: 130°C Z		<ul> <li>D: Selected Heater</li> <li>NGE: -50 to 500 °C, off</li> <li>-58 to 932 °F, off</li> <li>'IONS: Heater Setpoint must not be off.</li> </ul>
	This function sets the High Temperature Alarm <i>Heater Setpoint</i> . To disable this alarm, set the v. Temperature is greater than or equal to this setp activated and a <b>HIGH TEMPERATURE ALA</b> Status messages. The alarm deactivates when the setpoint.	setpoint. <i>It must be greater than the</i> alue to <b>off</b> . When the Heater Control point, the High Temperature Alarm is <b>RM</b> message is added to the System
LOW CURRENT ALARM: 10.5A <i>Æ</i>	MESSAGE NO:S1-07APPLIES TODEFAULT VALUE:offVALUERANDISPLAY MODE:AllRESTRICTThis function sets the Low Current Alarm setCurrent Alarm setpoint. To disable this alarm, setCurrent Alarm setpoint.To disable this setpoint, thea LOW CURRENT ALARM message is addedalarm deactivates when the Heater Current risesrange is in 0.5 A increments.Note: This setpoint is based on the heater at 1or Power Limit is enabled, all current measupower, based on a constant resistive load, besetpoint.	NGE: 0.5 to 30.0/100.0 A, off IONS: None point. <i>It must be less than the High</i> set the value to <b>off</b> . When the Heater Low Current Alarm is activated and d to the System Status messages. The above this alarm setpoint. The value 00% power. <i>If Proportional Control</i> <i>rements will be converted to 100%</i>
B: LOW CURRENT ALARM: 10.5A <i>Æ</i>	MESSAGE NO:S1-08APPLIES TODEFAULT VALUE:offVALUERANDISPLAY MODE:AllRESTRICTIONThis function sets the phase B: Low Current Alarmphase B: High Current Alarm setpoint. To discWhen the phase B: Heater Current is less than ofLow Current Alarm is activated and a <b>B: LOW</b> CUto the System Status messages. The alarm deatCurrent rises above this alarm setpoint. The valNote: This setpoint is based on the heater at 1or Power Limit is enabled, all current measupower, based on a constant resistive load, besetpoint.	NGE: 0.5 to 30.0/100.0 A, off ONS: MS2102-1TXHx panel arm setpoint. <i>It must be less than the</i> able this alarm, set the value to <b>off</b> . or equal to this setpoint, the phase B: <b>URRENT ALARM</b> message is added activates when the phase B: Heater ue range is in 0.5 A increments. 00% power. <i>If Proportional Control</i> rements will be converted to 100%

C: LOW CURRENT ALARM: 10.5A 🗷	MESSAGE NO: S1-09 APPLIES TO: Selected Heater DEFAULT VALUE: off VALUE RANGE: 0.5 to 30.0/100.0 A, off DISPLAY MODE: All RESTRICTIONS: MS2102-1TXHx panel This function sets the phase C: Low Current Alarm setpoint. <i>It must be less than the</i> <i>phase C: High Current Alarm setpoint.</i> To disable this alarm, set the value to <b>off</b> . When the phase C: Heater Current is less than or equal to this setpoint, the phase C: Low Current Alarm is activated and a <b>C: LOW CURRENT ALARM</b> message is added to the System Status messages. The alarm deactivates when the phase C: Heater Current rises above this alarm setpoint. The value range is in 0.5 A increments. <i>Note: This setpoint is based on the heater at 100% power. If Proportional Control</i> <i>or Power Limit is enabled, all current measurements will be converted to 100%</i> <i>power, based on a constant resistive load, before being compared to the alarm</i>
HIGH CURRENT ALARM: 15.0A &	MESSAGE NO:S1-10APPLIES TO:Selected HeaterDEFAULT VALUE:offVALUERANGE:0.5 to 30.0/100.0 A, offDISPLAY MODE:AllRESTRICTIONS:NoneThis function sets the High Current Alarm setpoint. It must be greater than the LowCurrent Alarm setpoint.To disable this alarm, set the value to off. When the HeaterCurrent is greater than or equal to this setpoint, the High Current Alarm is activatedand a HIGH CURRENT ALARM message is added to the System Status messages.The alarm deactivates when the Heater Current falls below this alarm setpoint. Thevalue range is in 0.5 A increments.Note: High current alarm is disabled when proportional control, or powerlimitfunctions are operating the heater below 100% duty cycle to prevent erroneousalarms at low duty cycles.
B: HIGHCURRENT ALARM: 15.0A 🗷	MESSAGE NO:S1-11APPLIES TO:Selected HeaterDEFAULT VALUE:offVALUE RANGE:0.5 to 30.0/100.0 A, offDISPLAY MODE:AllRESTRICTIONS:MS2102-1TXHx panelThis function sets the phase B: High Current Alarm setpoint. It must be greater than the phase B: Low Current Alarm setpoint. To disable this alarm, set the value to off.When the phase B: Heater Current is greater than or equal to this setpoint, the phase B: High Current Alarm is activated and a B: HIGH CURRENT ALARM message is added to the System Status messages. The alarm deactivates when the phase B: Heater Current falls below this alarm setpoint. The value range is in 0.5 A increments. Note: High current alarm is disabled when proportional control, or powerlimit functions are operating the heater below 100% duty cycle to prevent erroneous alarms at low duty cycles.
C: HIGHCURRENT ALARM: 15.0A 🗷	MESSAGE NO: S1-12 APPLIES TO: Selected Heater DEFAULT VALUE: off VALUERANGE: 0.5 to 30.0/100.0 A, off DISPLAY MODE: All RESTRICTIONS: MS2102-1TXHx panel This function sets the phase C: High Current Alarm setpoint. <i>It must be greater than</i> <i>the phase C: Low Current Alarm setpoint</i> . To disable this alarm, set the value to <b>off</b> . When the phase C: Heater Current is greater than or equal to this setpoint, the phase C: High Current Alarm is activated and a <b>C: HIGH CURRENT ALARM</b> message is added to the System Status messages. The alarm deactivates when the phase C: Heater Current falls below this alarm setpoint. The value range is in 0.5 A increments. <i>Note: High current alarm is disabled when proportional control, or powerlimit</i> <i>functions are operating the heater below 100% duty cycle to prevent erroneous</i> <i>alarms at low duty cycles</i> .

HIGH CURRENT TRIP: 15.0A <section-header></section-header>	MESSAGE NO:S1-13APPLIES TO:Selected HeaterDEFAULT VALUE:offVALUERANGE:0.5 to 30.0/100.0 A, offDISPLAY MODE:AllRESTRICTIONS:NoneThis function sets the High Current Trip setpoint. It must be greater than the LocCurrent Alarm setpoint and the High Current Alarm setpoint.To disable this trifunction, set the value to off. When the Heater Current is greater than or equal to the setpoint, the heater circuit is open, a High Current Trip Alarm is activated and a HIGHCURRENT TRIPALARM message is added to the System Status messages. This a latching alarm. When the cause of the alarm has been corrected, locate the alarm message in the Status Menu and press [RESET].Note: This setpoint is based on the heater at 100% power. If proportional control or Power Limit is enabled, all current measurements will be converted to to 1009 power, based on a constant resistive load, before being compared to the alarm setpoint.
B: HIGH CURRENT TRIP: 15.0A <section-header></section-header>	MESSAGE NO:S1-14APPLIES TO:Selected HeaterDEFAULT VALUE:offVALUE RANGE:0.5 to 30.0/100.0 A, offDISPLAY MODE:AllRESTRICTIONS:NoneThis function sets the phase B: High Current Trip setpoint. It must be greater thatthe phase B: Low Current Alarm setpoint and the phase B: High Current Alarnsetpoint.To disable this trip function, set the value to off. When the phase B: HeateCurrent is greater than or equal to this setpoint, the heater circuit is open, a B: HigCurrent Trip Alarm is activated and a B: HIGH CURRENT TRIPALARM messageadded to the System Status messages. This is a latching alarm. When the cause of thealarm has been corrected, locate the alarm message in the Status Menu and prese[RESET].Note: This setpoint is based on the heater at 100% power. If proportional controlor Power Limit is enabled, all current measurements will be converted to to 1009power, based on a constant resistive load, before being compared to the alarn
C: HIGH CURRENT TRIP: 15.0A 🗷	MESSAGE NO:S1-15APPLIES TO:Selected HeaterDEFAULT VALUE:offVALUERANGE:0.5 to 30.0/100.0 A, offDISPLAY MODE:AllRESTRICTIONS:NoneThis function sets the phase C:High Current Trip setpoint. It must be greater thatthe phase C:Low Current Alarm setpoint and the phase C:High Current Alarnsetpoint.To disable this trip function, set the value to off. When the phase C: HeaterCurrent is greater than or equal to this setpoint, the heater circuit is open, a C:HigCurrent Trip Alarm is activated and a C:HIGH CURRENT TRIPALARM messageadded to the System Status messages.This is a latching alarm. When the cause of thealarm has been corrected, locate the alarm message in the Status Menu and prese[RESET].Note:This setpoint is based on the heater at 100% power.If proportional controlor Power Limit is enabled, all current measurements will be converted to to 1009power, based on a constant resistive load, before being compared to the alarn
POWER LIMIT CURRENT: 20.5A &	MESSAGE NO: S1-16 APPLIES TO: Selected Heater DEFAULT VALUE: off VALUE RANGE: 0.5 to 30.0/100.0 A, off DISPLAY MODE: Advanced RESTRICTIONS: None This function sets the maximum average current that flows in the heater circuit. It useful for limiting the inrush current of self regulating cable or reducing the pow- output of constant wattage heaters. Set the value below the breaker rating or to th maximum power desired (Wattage=Heater Volatge x Power Limit value). The value range is in 0.5 A increments

range is in 0.5 A increments.

GROUND FAULT TRIP: 100mA 🗷	MESSAGE NO:S1-17APPLIES TO:Selected HeaterDEFAULT VALUE:30 mAVALUERANGE:10 to 1000 mA,offDISPLAY MODE:AdvancedRESTRICTIONS:NoneThis function sets the Ground Fault Trip setpoint. It must be greater than the GroundFault Alarm setpoint.When the Ground Fault Current is greater than or equal to thissetpoint, the heater circuit is opened, the Ground Fault Trip Alarm is activated and aGROUND FAULT TRIP message is added to the System Status messages. This is alatching alarm. When the cause of the alarm has been corrected, locate the alarm message in the Status Menu and press [RESET]. The value range is in 1 mA increments.
GROUND FAULT ALARM: 20mA &	MESSAGE NO:SI-18APPLIES TO:Selected HeaterDEFAULT VALUE:20 mAVALUE RANGE:10 to 1000 mA, offDISPLAY MODE:AllRESTRICTIONS:NoneThis function sets the Ground Fault Alarm setpoint. It must be less than the Ground Fault Trip setpoint. To disable this alarm, set the value to off. When the Ground Fault Current is greater than or equal to this setpoint, the Ground Fault Alarm is activated and a GROUND FAULT ALARM message is added to the System Status messages. The alarm deactivates when the Ground Fault Current falls below this alarm setpoint. The value range is in 1 mA increments.
TRACECHECK CYCLE TIME: 4 hours	MESSAGE NO: S1-19 APPLIES TO: Selected Heater DEFAULT VALUE: off VALUE RANGE: 1 to 24 hours, off DISPLAY MODE: Advanced RESTRICTIONS: None This function sets the frequency at which TraceCheck is activated. TraceCheck is a feature that exercises the system by automatically applying power to the heater if off for about 30 seconds. If an alarm condition is detected during this period, the TraceCheck™Alarm is activated and a <b>ALARM DURING TRACECHECK</b> message is added to the System Status messages. If a ground fault is detected, the heater circuit is opened. This is a latching alarm. To clear the alarm, locate the alarm message in the Status Menu and press [RESET]. To disable this feature, set the value to <b>off</b> . TraceCheck™ decreases maintenance by providing an early warning of problems that would otherwise go undetected until the heater was needed.
LOW VOLTAGE ALARM: 100 V &	MESSAGE NO:S1-20APPLIES TO:Selected HeaterDEFAULT VALUE:offVALUERANGE:85 to 300 V, offDISPLAY MODE:AllRESTRICTIONS:HTR SET VOLTAGE is set to measured.This function sets the Low Voltage Alarm setpoint. To disable this alarm, set the value to off. When the Heater Voltage is less than or equal to this setpoint, the Low Voltage Alarm is activated and a LOW VOLTAGE ALARM message is added to the System Status messages. The alarm deactivates when the Heater Voltage rises above this alarm setpoint.
HTR SET VOLTAGE: measured 🖉	MESSAGE NO:S1-21APPLIES TO:Selected HeaterDEFAULTVALUE:measuredVALUERANGE:100 to 600 V, measuredDISPLAY MODE:AllRESTRICTIONS:NoneThis function sets the value (100~600V) of heater voltage in the statistics calculationof the selected heater.When it is set to <i>measured</i> , the measured supply voltageacross terminal 2 & 3 on the Control Module is used in the calculation of heater

statistics and low voltage alarm.

#### Heater Setup

SETPOINTS: HEATER SETUP	MESSAGE NO: DEFAULT VALUE: DISPLAY MODE: This message displa	Advanced	APPLIES TO: VALUE RANGE: RESTRICTIONS: of the sub-menu wh	
SELECT HT M-1 & NONAME	in a form of M-N. M circuit within the C	Advanced s the heater circ I is the Module ontrol Module a heater circuit	Number of the Con Press [VALUE ①]	
HEATER NAME: NONAME &	the heater circuit. T enter one at a time selected. Press [VA]	Advanced ne Heater Nam he Heater Nan from left to rig LUE î ] or [VA g [STORE]. Co	the consists of 16 alg ght. The cursor indi $LUE \ \ ]$ to change intinue in this way un	que, identifiable tag or label for bhanumeric characters that you cates which character is being the character. Move to the next ntil all 16 characters are entered.
MASTER OVERRIDE: off <i>Z</i>	Override input. Th Master Override is a heater circuit opera Heater Setpoint. If are open, the heater This feature allows ambient temperature	Advanced e response of the Master Ove set to <b>off</b> or the tas normally be the Master Ove circuit is oper s selected circu re override. If	rride input respond Master Override in based on the Heater erride is set to <b>on</b> a ned regardless of th uits to be turned of the Heater Setpoin	Selected Heater on, off None the Control Module's Master ds to a contact closure. If the puts are shorted, control of the r Control Temperature and the and the Master Override inputs e Heater Control Temperature. ff for load shedding or for an t is set to <b>off</b> or <b>none</b> and the ts will have full control over the
PROPORTIONAL CONTROL: off <i>Z</i>	control. For critical t control by using th longer. With Prope	Advanced nizes temperature emperature ma is feature. Ho ortional Contro ter Setpoint, th	re overshoot and un intenance applicatio wever, the time to ol set to <b>on</b> , as the e percent duty cycl	Selected Heater on, off Heater Setpoint must not be off. dershoot for tighter temperature ns you can obtain more accurate reach Heater Setpoint may be e Heater Control Temperature e of the heater is reduced. With

Proportional Control set to off, on-off control is used.

AUTO TUNING	MESSAGE NO:	S2-06	APPLIES TO:	Selected Heater
PERIOD: off <i>Æ</i>	DEFAULT VALUE:	off	VALUERANGE:	1 to 24 hrs, off
	DISPLAY MODE:	Advanced	RESTRICTIONS:	Heater Setpoint must not be <b>off</b> .
	would automatically performance data e Period depends the heat tracing system	y adjust its prop very Auto Tur inertia time con is, the longo to <b>off</b> , the auto	portional control gat ning Period. The ex- postant of the heat t er the auto tuning to tuning feature is	the period is set, the controller in constant based on the system tact value of this Auto Tuning racing system. The slower the period should be. With Auto disabled and the proportional
	MESSAGE NO:	S2-07	APPLIES TO:	Selected Heater
DEADBAND 5C° 🖄	DEFAULT VALUE:	1 C° 2 F°	VALUE RANGE:	0 to 50 C° 0 to 90 F°
	DISPLAY MODE:	Advanced	RESTRICTIONS:	Proportional Control must be <b>off</b> . Heater Setpoint must not be <b>off</b> .
				ntrol. Decreasing the deadband increases the heater switching
	MESSAGE NO:	S2-08	APPLIES TO:	Selected Heater
IF RTD FAILS HEATER GOES: off <i>Æ</i>	DEFAULT VALUE: DISPLAY MODE:	off Advanced	VALUE RANGE: RESTRICTIONS:	on, off Heater Setpoint must not be off.
	temperature sensor For freeze protectio	has failed. In t n where there i	his case, it will set is no hazard from ov	Control Module detects if the the heater to its fail-safe state. yer heating, set to <b>on</b> to prevent ing, this setting should be set to
	MESSAGE NO:	S2-09	APPLIES TO:	Control Module
RTD MODE:	DEFAULT VALUE:	1 RTD	VALUERANGE:	See list below
1 RTD 🔊	DISPLAY MODE:	Advanced		Dual RTD per circuit mode
	This function sets h inputs as follows.	ow the Heater	Control Temperatu	re is derived from dual RTD
	VALUE		Heater Control Te	mperature
	1 RTD		RTD-A	Inperature
	RTD B HT cutoff		RTD-A but less th	an RTD-B
	2 RTDs, lowest		Minimum of RTD-	A&RTD-B
	2 RTDs, highest		Minimum of RTD-	
	2 RTDs, averaged		Average of RTD-A	
	2 RTDs, backup	staff is calcuta	RTD-A if okay, els	
				are is compared with the high I to or greater than the high
				ardless if RTD-A temperature
	is less than the hea		0	*

# System Setup

SETPOINTS: SYSTEM SETUP	MESSAGE NO: DEFAULT VALUE: DISPLAY MODE: A This message displa	All	APPLIES TO: VALUE RANGE: RESTRICTIONS: f the sub-menu wh	
DISPLAY MODE: advanced user 🗷	messages are displa Each message liste message. Advanced	yed. If set to <b>no</b> d in this chapt	RESTRICTIONS: ssages are displaye ormal user, only the ter shows the Disp	Control Module VALUERANGE: advanced user, normal user None ed. If set to <b>advanced user</b> , all basic messages are displayed. blay Mode required to see the play mode to <b>advanced user</b> to
DEFAULT DISPLAY: System Status 🗷	view the message. MESSAGE NO: DEFAULT VALUE: DISPLAY MODE:	S3-03 System statu Advanced	APPLIES TO: s VALUE RANGE: RESTRICTIONS:	Control Module See values below Heater Temp messages are not displayed if Heater setpoint is <b>off</b> .
	This function species pressed for the Disp VALUE System status Heater status Heater temp			DISPLAYED
DISPLAY TIMEOUT: 60 seconds <i>Æ</i>				Control Module 5 to 600 s, off None y press, to automatically return nction, set the value to <b>off</b> .
SCAN TIME: 2 seconds 🖉	MESSAGE NO: DEFAULT VALUE: DISPLAY MODE: This function sets t Select a value that i			splay of successive messages.
TEMPERATURE UNITS: Celcius <i>Æ</i>				Control Module Celsius, Fahrenheit Heater Setpoint must not be <b>off</b> . All temperatures are displayed
COST PER kWh: \$0.05 K	MESSAGE NO: DEFAULT VALUE: DISPLAY MODE:	S3-07 \$0.05 Advanced	APPLIES TO: VALUE RANGE: RESTRICTIONS:	degrees Fahrenheit (°F). Control Module \$0.01 to \$0.50 None ler uses this value to calculate

STAGGER START: off <i>Æ</i>		Advanced gers the power is value is set	to "on", the second	its to eliminate tripping of the d heater will be turned on one
BAUD RATE: 1200 🖉		Advanced e communication		Control Module 600,1200,2400,4800,9600 None S-485 serial port. All controllers the same baud rate.
ALARM LIGHT MODE: alarm: off <i>Æ</i>	light output is desig light is <b>on</b> in a no ala setting works best v out LED generates a alarm condition and the alarm light when	Advanced mines the respo gn to drive a 5V arm condition a vith a green LE an alarm condit d turns <b>on</b> when n alarms are pro <b>m flash/off</b> fla	/dc LED. If the value and turns off when all D for fail-safe mode ion. Value alarm on a larms are present esent and turns on the safes the alarm light	Control Module alarm:off, alarm:on flash/on, flash/off None ht output to an alarm. The alarm arms are present. The <b>alarm off</b> e where loss of power or a burnt t, turns the alarm light <b>off</b> in a no t. Value <b>alarm flash/on</b> flashes he alarm light when there are no t when alarms are present and
ALARM CONTACTS: MECH:NO & SS:N/A &	MESSAGE NO: DEFAULT VALUE:	S3-11 MECH:NC SS:N/A	APPLIES TO: VALUERANGE:	Control Module MECH:NO SS:N/A MECH:NO SS:N/A MECH:NC SS:N/A MECH:NC SS:N/A,
	closed (NC). MECI the Control Module	H refers to the r e. SS refers to t le, the contact	nechanical alarm co he solid state alarm closes during alarr	
SET MODULE NUMBER: 1 🗷	communicate along must have a uniqu	Advanced ges the Module g with other mo e address to en	dules to a central co nsure only one mo	Control Module 1-250 None trol Module. If a controller is to mputer or display, each module dule attempts to communicate communication is the module
FIRMWARE VERSION D0-00-00	MESSAGE NO: DEFAULT VALUE: DISPLAY MODE: This message displ	Advanced	APPLIES TO: VALUE RANGE: RESTRICTIONS: re version number.	Control Module N/A None

MANUAL VERSION 1501-0019	MESSAGE NO: DEFAULT VALUE: DISPLAY MODE: This message displ	Advanced	APPLIES TO: VALUERANGE: RESTRICTIONS: or manual version o	
FOR ASSISTANCE: (403) 735-9555	MESSAGE NO: DEFAULT VALUE: DISPLAY MODE: This message displ	Advanced	APPLIES TO: VALUERANGE: RESTRICTIONS: telephone number	
Setpoint Tests				
SETPOINTS TEST	MESSAGE NO: DEFAULT VALUE: DISPLAY MODE: This message displ	Advanced	APPLIES TO: VALUE RANGE: RESTRICTIONS: of the sub-menu wh	
MANUAL HEATER: disabled 🗷		Advanced ally overrides h		intenance purposes. For normal
				e, the heater is forced <b>on</b> for the e heater is forced on until you
MANUALALARM: disabled 🖉	MESSAGE NO: DEFAULT VALUE:		APPLIES TO: VALUERANGE:	Selected Control Module 1 to 24 hrs, disabled, on continuously
	normal operation, s forced into alarm s	set to <b>disable</b> . tate for the selected into alarm	If you select a period ected interval. If you n state until you so	for maintenance purposes. For od of time, the alarm output is ou select <b>on continuously</b> , the elect <b>disabled</b> . Alarm state is
GF TEST test now <i>Æ</i>	MESSAGE NO: DEFAULT VALUE:	S4-04 disabled	APPLIES TO: VALUE RANGE:	Control Module 1 to 24 hrs, test now, disabled
	ensure proper opera applies an ac curren fault currents. If the Test Alarm is activ sages. This is a lat	tion. When the t to the ground c Control Modu ated and a GF ching alarm. V	e ground fault test is fault transformer an ile does not see the CT message is ad When the cause of	

detected, no alarm message is displayed.

locate the alarm message in the Status Menu and press [RESET]. If there is no problem

### Overview

The MS-2102 is capable of generating many different types of alarms. In this chapter, alarms are organized in three groups: trip or failure, heater and warning. Each group represents a level of severity with the trip or failure type being extremely critical, the process type requiring some attention and warning type indicating those that do not require immediate attention. Each group is detailed by section throughout this chapter.

Access alarms by pressing [STATUS] where the total number of alarms is displayed. You must review each alarm by pressing [MESSAGE  $\oplus$ ] several times, each time displaying information about each alarm including the alarm name and reason for the alarm.

# **Trip or Failure Alarms**

GROUND FAULT ALARM

GROUND FAULT TRIP

SELF TEST FAILURE ALARM

> GF TEST FAIL

RELAY FAILURE ALARM

RTD FAILURE ALARM The measured ground fault current is greater than or equal to the Ground Fault Alarm setpoint or, the ground fault current is greater than the maximum value range.

- $\checkmark$  Check that the setpoint is appropriate for the length and type of cable.
- $\checkmark$  Check for wet or damaged heating cable, power connections, splices or tees.
- $\checkmark$  Test for correct ground fault measurement.

The measured ground fault current is greater than or equal to the Ground Fault Trip setpoint.

- $\checkmark$  Check that the setpoint is appropriate for the length and type of cable.
- $\checkmark$  Check for wet or damaged heating cable, power connections, splices or tees.
- $\checkmark$  Test for correct ground fault measurement.

A memory or CPU failure has occurred.

✓ The Control Module needs repair.

Ground fault monitoring function did not detect the GF test current.

- $\checkmark$  Ground fault current transformer may be faulty.
- $\checkmark$  Ground fault monitoring function may be faulty and controller needs repair.

The heater current is greater than or equal to 0.1 A when the heater circuit is off.

- ✓ Check SCRs for failure in short circuit state.
- $\checkmark$  Controller may be faulty and needs repair.

The temperature derived from the RTD resistance has exceeded 500  $^{\circ}\text{C}$  or dropped below -50  $^{\circ}\text{C}$ 

- ✓ Check for damaged RTD, cable or open/short connection.
- ✓ Check middle lead of RTD (terminal 7 or 11) for open connection.
- ✓ Pipe temperature has exceeded 500°C.
- ✓ Pipe temperature has dropped below  $-50^{\circ}$ C.
- $\checkmark$  Test the RTD input.

#### Process Alarms

HIGH TEMPERATURE ALARM



HIGH CURRENT ALARM

# LOW CURRENT ALARM

#### LOW VOLTAGE ALARM

#### Warning Alarms

ALARM DURING TRACECHECK The Heater Control Temperature is greater than or equal to the High Temperature Alarm setpoint.

- $\checkmark$  Check that the alarm setpoint is correct.
- ✓ Test for correct RTD operation.
- $\checkmark$  Check the heat trace design.

The Heater Control Temperature is less than or equal to the Low Temperature Alarm setpoint.

- $\checkmark$  Check that the alarm setpoint is correct.
- ✓ Test for correct RTD operation.
- $\checkmark$  Check for damaged insulation or cladding.
- $\checkmark$  Check for damaged heat trace.
- $\checkmark$  Check the heat trace design.

The measured Heater Current, when the heater circuit is **on**, is greater than or equal to the High Current Alarm setpoint or, the Heater Current is greater than the maximum value range.

- $\checkmark$  Check that the alarm setpoint is correct.
- ✓ For self-regulating heating cable, the current varies substantially with temperature. Check that the alarm setpoint accounts for this variation or use the heat trace curve function.
- ✓ Test for correct current measurement.

The measured Heater Current, when the heater circuit is **on**, is less than or equal to the Low Current Alarm setpoint.

- $\checkmark$  Check that the alarm setpoint is correct.
- ✓ For self-regulating heating cable, the current varies substantially with temperature. Check that the alarm setpoint accounts for this variation or use the heat trace curve function.
- ✓ Test for correct current measurement.
- ✓ For parallel resistance heating cable, check for broken cable, failed splice or tee connection.
- ✓ For zone-type heating cable, check for failed zones.

The measured circuit voltage is less than or equal to the Low Voltage Alarm setpoint.

- ✓ Check for voltage input failure by measuring the voltage at the Heater Voltage terminals.
- ✓ If a control transformer is used for input power, check wiring configuration to the transformer.
- ✓ Check loading on power system. Possible brown out.

One of the following alarms occurred during the TraceCheck<sup>TM</sup> cycle. Refer to the alarm details above for the individual alarm.

- ✓ TC SWITCH SHORTED ALARM
- ✓ TC LOSS OF CONTINUITY
- ✓ TC HIGH CURRENT ALARM
- ✓ TC LOW CURRENT ALARM
- ✓ TC GROUND FAULT ALARM
- ✓ TC GROUND FAULT TRIP

#### **Reset Alarms**

Some alarms such as TraceCheck type, Ground Fault Trip and Ground Fault test are latching. The alarm remains on the display even after the alarm condition has gone away. Latch alarms require you to acknowledge or reset the alarm. To reset alarms,

1. Press [STATUS].

2. Press [MESSAGE  $\clubsuit$ ] to locate the alarm message.

3. Press [RESET].

The alarm should be cleared from the display unless the alarm condition is still present.

#### Overview

The MS-2102 heat trace controller communicates with computerized equipment such as programmable logic controllers, desktop computers or man-machine interfaces using Modicon Modbus protocol. The MS-2102 supports a subset of the Remote Terminal Unit (RTU) format of the protocol that provides extensive monitoring, programming and control functions using read and write register commands. The MS-2102 always acts as a slave device such that it does not initiate communications; it only listens and responds to requests issued by a master computer.

#### **Physical Layer**

Modbus protocol is hardware independent so that the physical layer can be a variety of hardware mediums such as RS-485, RS-422, RS-232 or fiber optics. The MS-2102 is configured with one RS-485 port. Refer to *Chapter 2 Installation*, for wiring details.

Each data bit is transmitted in an asynchronous format consisting of 1 start bit and 1 stop bit to produce a 10-bit data frame. This is important for transmission through modems at higher bit rates (11 bit frames are not supported by some modems at bit rates greater than 300bps). The baud rate on the serial port is programmable. Baud rates of 1200, 2400, 4800 and 9600 are available. Parity is fixed to *none*. Refer to *Chapter 6 Setpoint Values*, for details on baud rate configuration.

The master device must know the address (module number) of the slave device in order to communicate with it. The MS-2102 does not respond to requests from the master unless the request matches the controller's module number. Refer to *Chapter 6 Setpoint Values*, for details on setting the module number.

#### **Modbus Protocol**

This section discusses the Modbus protocol.

<u>Data Structure</u>: Data communications take place in packets, which consist of multiple asynchronously framed data. The master sends a packet to the slave and the slave responds with a packet. End of packet is determined by a **dead time** on the data highway.

Modbus packet Format:

1 byte
1 byte
N bytes
2 bytes
3.5 bytes transmission time

<u>Slave Address</u>: This is referred to as module number on the MS-2102 that is to receive packets sent by the master and respond to the request. The module number must be unique for each controller on the data highway to avoid bus contention. The module number is user defineable from 1 to 250; refer to *Chapter 6 Setpoint Values* for details. Only the addressed slave responds to a packet that starts with its module number.

<u>Function Code:</u> The function code tells the slave what action to perform. Refer to supported functions in this section for details.

<u>Data:</u> The number of bytes depends on the function code. Data include setpoints, Measured Values, or alarm status or addresses sent between the master and slave.

<u>CRC:</u> Short for Cyclic Redundancy Check, CRC is an industry standard method used for error detection. Modbus RTU includes a 16-bit CRC with every packet. When a slave receives a packet that is in error due to CRC the slave device ignores the packet to prevent any erroneous operation.

<u>Dead Time:</u> End of transmission of a packet is determined when no data is received for a period of 3.5 byte transmission times (about 15ms at 2400 baud and 4ms at 9600 baud). Consequently, the transmitting device must not allow gaps between bytes longer than this interval. Once the dead time has expired without a new byte transmission, all slaves start listening for a new packet from the master except the addressed slave.

<u>Supported Function Codes:</u> The following functions are supported by MS-2102 firmware:

CODE	Address Range	Туре	Interpretation
03	40001-50000	Holding Register	Read variable registers
05	1-10000	Output Coil	Reset heater alarm or statistics
06	40001-50000	Holding Register	Store value into one variable register
16	40001-50000	Holding Register	Store value into a group of variable registers

Note: Any slave module must have a unique address within 1 - 250. Address 255 is reserved for module commissioning & addressing.

#### Function code 03 - Read Variable Registers

Modbus implementation: Read Holding Registers MS-2102 implementation: Read variable registers In Modbus, Read Holding Registers is used to obtain current binary value in one or more holding registers. It assumes that each register is a 16-bit register. For the MS-2102 implementation of Modbus, this function obtains value from one variable register or values from a group of variable registers. This command can access only the variable registers with Memory Location Index between 0 (the first index in Module Setup Group) and 164 (the last index in Heater Statistics Group). Any attempts to read a variable register with Memory Location Index beyond the above range results in an error response in return.

Master Query: It consists of module address, function code, memory location index of the starting variable register, number of variable registers to be read and CRC error check.

Slave Response: It consists of module address, function code, quantity of data bytes to be returned, data value and CRC error check.

Message Format and Example:

Request slave 11 to respond with local heater #1's low current alarm level. Suppose heater #1's low temperature alarm level is 10.1 °C. Here are transmission and response messages:

Master Transmission	Bytes	Message Contents (Decimal)
Slave Address	1	11 (message to slave 11)
Function Code	1	3 (command "read variable registers")
Memory Location Index	2	73 (refer to register storing local heater #1's low temp level)
Number of Registers	2	1 (a 2-byte variable)
CRC	2	????

Slave Response	Bytes	Message Contents (Decimal)
Slave Address	1	11 (message from slave 11)
Function Code	1	3 (command "read variable registers")
Quantity of Data Bytes	1	2 (2 bytes)
Data Value	2	101 (10.1 °C)
CRC	2	????

#### Function code 05 - Reset Heater Alarms & Statistics

Modbus implementation: Force Single Coil MS-2102 implementation: Reset heater alarms &

statistics

In Modbus, Force Single Coil forces logic coil to a state of ON or OFF.

For the MS-2102 implementation of Modbus, this function resets the heater alarm or statistics. Once an MS-2102 control module is in use, it keeps monitoring heater alarms and updating heater statistics. Some of the alarms are latched even after the alarm condition no longer exists. It's up to the user to reset those latched alarms and some statistics. By sending a data value 65280 (FF00 Hex) to any variable register with Memory Location Index between 165 and 186 (Heater Alarm Reset & Statistics Reset Group), the corresponding alarm or statistics will be reset. Sending a data value 0 to any register within the above range is legal but will have no effect. Sending a data value other than 65280 and 0 to any register within the range or sending any data to any register beyond the range is illegal and will result in an error response in return.

Master Query: It consists of module address, function code, memory location index of the variable register, data value FF00 Hex and CRC error check.

Slave Response: It consists of module address, function code, memory location index of the variable register, data value FF00 Hex and CRC error check.

Message Format and Example:

Request slave 200 to reset local heater #10's minimum temperature. Here are transmission and response messages:

Master Transmission	Bytes	Message Contents (Decimal)
Slave Address	1	200 (message to slave 200)
Function Code	1	5 (command "reset heater alarm and statistics")
Memory Location Index	2	173 + (10-1) * 190
Data Value	2	65280 (FF00 Hex)
CRC	2	????

Slave Response	Bytes	Message Contents (Decimal)
Slave Address	1	200 (message from slave 200)
Function Code	1	5 (command "reset heater alarm and statistics")
Memory Location Index	2	173 + (10-1) * 190
Data Value	2	65280 (FF00 Hex)
CRC	2	????

#### Function code 06 - Store a Value into one Variable Register

Modbus implementation: Preset Single Register MS-2102 implementation: Store a value into one variable

register

In Modbus, Preset Single Register places a specific binary value into a holding register. For the MS-2102 mplementation of Modbus, this function is used to store a value into one variable register with Memory Location Index in Module Setup Group (0 to 30), Module Setting Group (31 to 43) and Heater Setpoints Group (71 to 108). Any attempts to store a value into a variable register beyond the above range results in an error response. Master Query: It consists of module address, function code, memory location index of the variable register, data value and CRC error check.

Slave Response: It consists of module address, function code, memory location index of the variable register, data value and CRC error check.

Message Format and Example:

Request slave 98 to change its local heater #10's heater setpoint to 30 °C. Here are transmission and response messages:

Master Transmission	Bytes	Message Contents (Decimal)
Slave Address	1	98 (message to slave 98)
Function Code	1	6 (command "store a value into one variable register")
Memory Location Index	2	72 + (10-1) * 190
Data Value	2	300 (30.0°C)
CRC	2	????
Slave Response	Bytes	Message Contents (Decimal)
Slave Address	1	98 (message from slave 98)
		30 (message nom siave 30)
Function Code	1	6 (command "store a value into one variable register")
Function Code Memory Location Index	1 2	6 (command "store a value into one
Memory Location	1 2 2	6 (command "store a value into one variable register")

#### Function code 16 - Store Values into a Group of Variable Registers

Modbus implementation: Reset Multiple Registers MS-2102 implementation: Store values into a group

Variable registers

In Modbus, Preset Multiple Registers places specific binary values into a series of consecutive holding registers. It assumes that each register is 16-bit register. For the MS-2102 implementation of Modbus, it is the same thing. Using this command, a group of consecutive variable registers can be assigned to their desired values. This command can access only the variable registers with Memory Location Index in Module Setting Group (31 to 43) and Heater Setpoints Group (71 to 108). Any attempts to store values into variable registers with Memory Location Index beyond the above range results in an error response in return.

Master Query: It consists of module address, function code, memory location index of the starting variable register, number of variable registers to be stored, quantity of data bytes to be stored, data value and CRC error check.

Slave Response: It consists of module address, function code, memory location index of the starting variable register, quantity of data bytes stored and CRC error check.

Message Format and Example:

Request slave 11 to set local heater #1's low temperature alarm level to 5 °C and high temperature alarm level to

Master Transmission	Bytes	Message Contents (Decimal)
Slave Address	1	11 (message to slave 11)
Function Code	1	16 (command "store value to a group of variable registers")
Memory Location Index	2	73
Number of Registers	2	2 (2 variable registers)
Quantity of Data Bytes	1	4 (4 bytes)
Data Value	4	50 (50°C for low temp alm level) 3000 (300°C for high temp alm level)
CRC	2	????

Slave Response	Bytes	Message Contents (Decimal)
Slave Address	1	11 (message from slave 11)
Function Code	1	16 (command "store value to a group of variable registers")
Memory Location Index	2	73
Number of Registers	2	2 (2 variable registers)
CRC	2	????

#### 300 °C. Here are transmission and response messages: Module Commissioning & Addressing

A MS-2102 module contains a whole set of setpoints and module settings. It also has its assigned module address. Any customer equipment (Master) with Modbus communication protocol can reset all heater setpoints and module settings to their default values, read a module's assigned address or assign a new address to a module. It is called Module Commissioning & Addressing. To avoid any careless errors, only the module that is in listening to new address mode (The ADDRESS ENABLE dip switch is set to the enable position) responds to Module Commissioning & Addressing commands. To perform module commissioning on an MS-2102 module, a Master must use Function 06 to store a value of 0 into the variable register with Memory Location Index 187. To read a module's address, a Master must use Function 03 to read the value stored in the variable register with Memory Location Index 188.

To assign a new address to a module's address, a Master must use Function 06 to store a desired address into the variable register with Memory Location Index 189. Note: The slave address of the above module commissioning & addressing commands is fixed to 255. Message Format and Example:

Assign a module to a new address 230. Here are transmission and response messages:

Master Transmission	Bytes	Message Contents (Decimal)
Slave Address	1	255 (always 255)
Function Code	1	6 (command "store a value into one variable register")
Memory Location Index	2	189 (refer to the register for assigning address)
Data Value	2	230 (new address)
CRC	2	????

Slave Response	Bytes	Message Contents (Decimal)
Slave Address	1	255 (always 255)
Function Code	1	6 (command "store a value into one variable register")
Memory Location Index	2	189 (refer to the register for assigning address)
Data Value	2	230 (new address)
CRC	2	????

#### MS-2102 Error Responses

If a MS-2102 module receives a transmission in which an error is indicated by framing, format, overrun or the CRC calculation, the module will not respond to the

transmission.

When a MS-2102 module detects an error other than a framing, format, overrun or CRC error, a response will be sent to the master. The most significant bit of the FUNC-TION CODE byte will be set to 1 (that is the function code sent from the slave will be equal to the function code sent from the master plus 128). The byte that follows it will be an exception code indicating the type of error that occurred.

The slave response to an error (other than CRC error) will

-		
be:Slave Response	Bytes	Message Contents (Decimal)
Slave Address	1	????
Function Code	1	????
Exception Code	1	????
CRC	2	????

The MS-2102 implements the following exception response codes.

01 - ILLEGAL FUNCTION

The function code transmitted by the master is not one of the functions supported by MS-2102.

02 - ILLEGAL MEMORY LOCATION INDEX

The index transmitted by the master is not allowable. 08 - ILLEGAL ADDRESS ENABLE DIP SWITCH POSITION

The address enable dip switch on MS-2102 controller is in the wrong position

#### **Modbus Memory Map**

Upon request, the Modbus Memory Map can be sent to customers from factory.

#### Overview

You can use the procedures in this chapter to verify the proper operation of the MS-2102. Although not a complete functional verification, these tests will check major operating functions. The scope of testing includes field testing of the controller inputs/outputs with and without heat tracing cable. Before commissioning the controller, read *Chapter2 Installation*. It provides important information about wiring, mounting and safety concerns. One should also become familiar with the controller as described in *Chapter 3 Getting Started* and *Chapter 6 Setpoint values*.

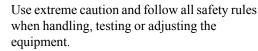
### Requirements

The test procedures outlined in this chapter verify functions related to field application. These functions include RTD inputs, heater output, ground fault, current and voltage monitoring. To facilitate field testing, it is recommended functions be turned *off* or *disabled*. It is not mandatory that field testing be done. However, we recommend procedures in section *Placing the Controller in Service* be performed for all installations to verify proper operation and function of the equipment.

#### **Safety Precaution**



Dangerously high voltages are present on the power input and output terminals capable of causing death or serious injury.





The controller uses components that are sensitive to electro-static discharges. When handling the unit, care should be taken to avoid contact with terminal blocks.

Installation Checks:

- 1. Check that the line voltage to the power inputs does not exceed the name plate ratings.
- 2. Check that the current draw of the heat trace cable does not exceed the name plate ratings.
- 3. Check that the grounding stud is properly connected to ground.

#### **RTD Input Test**

Equipment: Two Resistance Decade Boxes or RTD Simulator

#### To test RTD Input,

- 1. Disconnect the RTD(s) from the control module ensuring that the leads are adequately labelled.
- 2. Connect the resistance box as shown in figure 9.3.

Figure 9.1 Resistance versus Temperature in °C						
(DIN EN 60751 RTD)						

°C	R (ohms)	°C	R (ohms)	°C	R (ohms)
-40	84.27	80	130.89	200	175.84
-30	88.22	90	134.70	210	179.51
-20	92.16	100	138.50	220	183.17
-10	96.09	110	142.29	230	186.82
0	100.00	120	146.06	240	190.46
10	103.90	130	149.82	250	194.08
20	107.79	140	153.58	260	197.69
30	111.67	150	157.32	270	201.30
40	115.64	160	161.04	280	204.88
50	119.39	170	164.76	290	208.46
60	123.24	180	168.47	300	212.03
70	127.07	190	172.16		

# Figure 9.2 Resistance versus Temperature in °F (DIN EN 60751 RTD)

°F	R (ohms)	°F	R (ohms)	°F	R (ohms)
-40	84.27	160	127.50	360	169.29
-30	86.47	170	129.62	370	171.34
-20	88.66	180	131.74	380	173.39
-10	90.85	190	133.86	390	175.43
0	93.03	200	135.97	400	177.48
10	95.22	210	138.08	410	179.51
20	97.39	220	140.18	420	181.55
30	99.57	230	142.29	430	183.58
40	101.74	240	144.38	440	185.61
50	103.90	250	146.48	450	187.63
60	106.06	260	148.57	460	189.65
70	108.22	270	150.66	470	191.67
80	110.38	280	152.74	480	193.68
90	112.53	290	154.82	490	195.69
100	114.68	300	156.90	500	197.69
110	116.83	310	158.97		
120	118.97	320	161.04		
130	121.10	330	163.11		
140	123.24	340	165.17		
150	125.37	350	167.23		

# MS-2102

- 3. Choose a test temperature for each RTD input and select corresponding resistances for each of the resistance decade boxes using the table of RTD resistances in figure 9.1 and 9.2. The temperatures for each RTD should be different. For the RTD simulator, set the test temperature of each unit.
- 4. Turn on power to the controller.
- 5. Display the temperature of each RTD (MEASURED\OPERATING VALUES\HEATER CONTROL TEMP. The two values should agree with the selected temperatures within the accuracy of the controller and test equipment.
- 6. If there is a significant discrepancy, consult the factory for service.

#### Heater Voltage and Current Test (MS2102 controller only)

Equipment: one voltmeter one clamp-on ammeter adjustable load bank (240VAC/10kW) 240VAC/30A single phase variac

You can perform voltage and current measurement tests on the same test setup. Rather than using an adjustable load, you can use a fixed load in conjunction with a variac to adjust the input supply voltage.

To test heater 1 voltage and current,

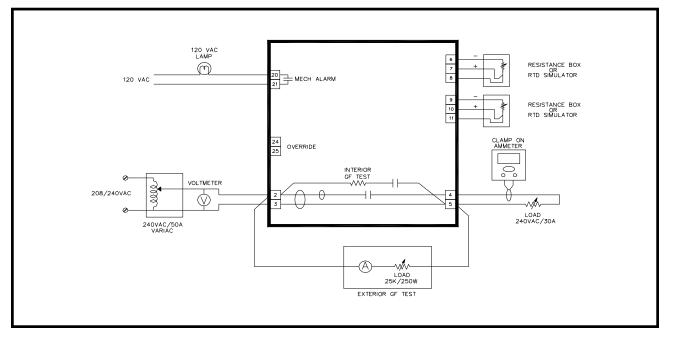
- 1. Disconnect any field wiring to terminals 2,3,4 and 5.
- 2. Connect the adjustable variac outputs to terminals 2 and 3. Connect the input supply of the variac to

Figure 9.3 Test Setup

either 208 or 240VAC. 120VAC will work but will not provide an effective test range for voltage testing.

- 3. Connect the load bank to terminals 4 and 5.
- 4. Connect the voltmeter across terminals 2 and 3.
- 5. Connect a clamp-on ammeter around one of the load cables.
- 6. Set the variac control for 120VAC and turn on the power.
- 7. Force the heater *on* by setting the manual heater function for **1 hour** (SETPOINT\SETPOINT TEST\MANUAL HEATER).
- 8. Display the heater current (MEASURED\OPERATING VALUES\HEATER CURRENT).
- 9. Adjust the variac control within the voltage range of the controller and compare the readings of the display with the ammeter.
- 10. Display the heater voltage (MEASURED\OPERATING VALUES\HEATER VOLTAGE).
- 11. Adjust the variac control to take another set of readings. Repeat until enough readings are taken to cover the range. Current and voltage readings should be within the accuracy of the controller and test equipment.
- 12. If there is a significant discrepancy, consult the factory for service.

The test procedures for heater 2 voltage and current are as same as the above procedures except that the power in/out terminals are 26, 27, 28 and 29. Also, the measured voltage for heater 2 is actually the input voltage of heater 1.



# Ground Fault Current Test

#### **Internal GF Test**

The controller comes with a ground fault test function that can be executed from the display (SETPOINTS\SETPOINT TEST\GF TEST). To run this test, 1. Select start now 2. Go to ground fault current (MEASURED\OPERATING VALUES\GROUND FAULT CURRENT).

A ground fault current appears for the duration of the test. If a heater does not see a ground fault current, it will initiate a GF CT failure alarm indicating the ground fault monitoring function is not working. The GF test function only verifies for operation and does not check for measurement accuracy. To check for accuracy, the next test procedure applies.

#### **External GF Test**

Using the same test setup for voltage and current measurement tests, add the following components to the test setup.

Equipment:

One 240R/250W power resistor (load bank used in previous procedure may be disconnected and used in place)

One AC ammeter (0-1A range)

To test heater 1 ground fault current,

- 1. Disconnect the load bank used in the previous test and reconfigure to 240R if possible.
- 2. Connect the load bank or power resistor to terminals 2 and 5 of the controller with the ammeter in series.
- 3. Set the variac control for 120VAC and turn on the power.
- 4. Force the heater on by setting the manual heater function for 1 hour (SETPOINT\SETPOINT TEST\MANUAL HEATER).
- 5. Change the GF trip alarm to **OFF** to prevent nuisance trips during the test. Reset ground fault trip alarms if necessary.
- 6. Display ground fault current (MEASURED\OPERATING VALUES\GROUND FAULT CURRENT).
- 7. Adjust the variac control to simulate various levels of ground fault currents through the load and compare readings from the display with the ammeter. Readings should be within the accuracy of the controller and test equipment.
- 8. If there is a significant discrepancy, consult the

factory for service.

9. Disconnect the load bank after the test.

The test procedures for heater 2 ground fault current are as same as the above procedures except that the load bank or power resistor should be connected to terminals 26 and 29, not 2 and 5.

### Alarm Output Test

#### **Mechanical Alarm**

Equipment: one 120VAC/100W Incandescent lamp with socket base

To test mechanical alarm contact,

- 1. Connect one lead of the lamp to terminal 20 of the controller.
- 2. Connect 120VAC to open lead of the lamp and terminal 21.
- 3. Power on the controller.
- 4. Ensure all alarms are turned off so that the controller is in no alarm condition.
- 5. Set SETPOINTS\SYSTEM SETUP\ALARM CONTACTS to MECH:NO SS:N/A. Lamp should be off.
- 6. Force alarm on by setting SETPOINT\SETPOINT TEST\ALARM TEST to **on for 1 hour**.
- 7. Lamp should be *on*.

# **Override Input Test**

Equipment:

one 120VAC Incandescent lamp

To test override input,

- 1. Connect the 120VAC incandescent lamp to terminals 4 and 5.
- 2. Power on the controller.
- 3. Make sure an RTD or simulator is connected to RTD1 input and set the equipment so that the control temperature is 100°C.
- 4. Check the heater 1 control temperature located at ACTUAL\OPERATING VALUES\HEATER CONTROL TEMP for 100°C.
- Set the heater 1 setpoint so that it is greater than the control temperature + deadband at SETPOINTS\OPERATING VALUES\HEATER SETPOINT. The deadband setting is located at SETPOINT\HEATER SETUP\DEADBAND.
- 7. Heater 1 should be *on*. Verify by checking the lamp is *on*.
- 8. Set SETPOINTS\HEATER SETUP\MASTER OVERRIDE to **on**.

- 9. Heater 1 should now be *off*. Verify by checking the lamp is *off*.
- 10. Short override input, terminals 24 and 25 with a short piece of wire.
- 11. Heater 1 should be *on*. Verify by checking the lamp is *on*.

#### **Placing the Controller in Service**

#### **Programming Setpoints**

Before testing the controller with heat trace cables, program setpoints. Ensure the program enable dip switch is set to ENABLED position. It is recommended that you program setpoints in the operating values group. For users who are not familiar with the control functions, advanced functions such as those in the heater setup group should be disabled during initial startup to simplify troubleshooting.

#### **Initial Startup**

After programming setpoints in the operating values group, the controller is ready for test. Check field connections to make sure they are correctly wired. Power on the controller and check the control temperatures on the display (MEASURED\OPERATING VALUES\HEATER CONTROL TEMP). Verify that the temperature readings are valid.

Assuming a heater circuit's pipe temperature is below the setpoint, the heater should be calling for heat. Check heater voltage (MEASURED\OPERATING

VALUES\HEATER VOLTAGE) on the display to verify with the line voltage.

Check heater current (MEASURED\OPERATING VALUES\HEATER CURRENT) on the display. If the controller is calling for heat, this value should be greater than zero; otherwise, a low current alarm appears. This is an indication the heater is not properly wired or functioning correctly. The display value should correspond to the expected current draw of the heat trace.

#### **Startup Problems**

Breaker Trip Due to Inrush:

If self-regulating heat trace is used, it is possible the display will show O.L. (overload) because of the in-rush current exhibit in the heat trace during cold startup. The heater current range is up to 30A so that you can monitor inrush current. The heater current drops as the pipe temperature warms up. If the circuit breaker trips during startup, the inrush current is too high for the breaker rating. Check the heat trace design to make sure the

breaker rating is appropriately sized. Trun on the STAGGER START function to reduce the inrush current.

#### Ground Faults:

Check ground fault current (MEASURED\OPERATING VALUES\GROUND FAULT CURRENT) on the display. Ground fault current should not be over 15mA; otherwise, ground fault trip or alarm appears on the display. To troubleshoot ground faults, check heat trace wiring and moisture in electrical junction boxes and connections.

# Low and High Current Alarms with Self-Regulating Cable:

Setting values for low and high current alarms with selfregulating cable is more complicated since the heater output varies with temperature. High current alarms may occur during startup due to inrush currents and low current alarms may result when steady-state current is reached (pipe temperature is near setpoint). To prevent nuisance high and low current alarms, the high current alarm should be turned off and low current alarm set below the current rating of the cable at setpoint temperature.

#### Low Temperature Alarm:

During startup, a low temperature alarm is expected as cold fluid in the pipe slowly warms up. As the pipe temperature increases and exceeds the low temperature alarm setting, the alarm turns off. Eventually, the pipe temperature reaches setpoint, at which point the heater turns off. If the low temperature alarm and heater is on consistently, it is possible the heat tracing is not supplying enough heat. Either a higher wattage heat trace or longer length is required.

#### High Temperature Alarm:

A high temperature alarm occurs when pipe temperature exceeds the high temperature alarm setting. This can be caused by high feed temperature of the fluid. Placement of the RTD sensor near a hot area or direct exposure to sunlight may also cause a high temperature alarm. In this situation, improper pipe heating results..

# Powerlimiting

You can use, powerlimiting when the total wattage of the heat trace cable is not required or to limit inrush current to the self-regulating cable. The powerlimit function is located at SETPOINT\HEATER SETUP\POWER LIMIT. A detail explanation of how this function operates is described in the *Chapter 1 Theory of Operation*. Powerlimiting is set by the desired operating current of

the heat trace. For powerlimit to work properly, the powerlimit current should be below the nominal current rating of the heat trace. For example, if the heat trace draws 20A at its rated voltage and the application only requires 75% of its rated output, a powerlimit current of 15A will achieve a 75% reduction in power. With the powerlimit current set, the controller attempts to clamp the output current at that value.

The minimum powerlimit current setting should be greater than 10% of the nominal load current. This is because powerlimiting operates in 10% resolution. Choosing a powerlimit current below 10% causes the heater not to turn on since the average heater current at 10% (minimum duty cycle) exceeds the powerlimit current setting.

Be aware of how current alarms operate with duty cycle changes. Low current alarm is based on the nominal current ratings of the heat trace, not the average current. The low current alarm function converts actual current readings to the expected current value of the heat trace operating at 100% duty cycle prior to comparing against alarm settings. When using powerlimit, the high current alarm is disabled to prevent false alarms due to measurement error of the algorithm at low duty cycles. The error is always positive and therefore does not affect low current alarms.

#### **Control Scheme**

The MS-2102 controller supports two types of control scheme: on/off and proportional. The default is on/off switching which is used for majority of the applications. When on/off switching is used, the deadband setting determines the heater turn off temperature above the heater setpoint and the heater turn on temperature below the heater setpoint. The deadband setting is user definable located at SETPOINTS\HEATER\SETUP\DEADBAND. In applications requiring tighter control, you can use proportional control. To enable proportional control, locate message SETPOINTS\HEATER SETUP\PROPORTIONAL CONTROL. There is no proportional gain setting as this is automatically set by the controller to minimize errors. For further details how the proportional control function operates, refer to Chapter 1 Theory of Operation.

#### RTD

In the event of complete RTD failure, the controller can force the heater to default on or off. This is defined by message SETPOINT\HEATER SETUP\IF RTD FAILS

HEATER GOES. The choice of **on** or **off** depends on the application.

#### **Cost of Power**

In order for the energy cost functions to provide correct information, you should enter the cost per KWh for electrical power at SETPOINT\SYSTEM SETUP\COST PER KWh.

#### **Completing the Installation**

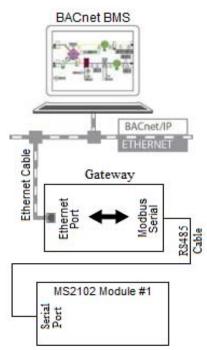
At this point, the controller has been setup with enough information to control and monitor the heat trace. Other functions are less critical and a description on how these function operate is located in *Chapter 6 Setpoint Values*. Read chapter 6 to gain an understanding of all the functions in order to customize the controller to the application requirements.

# Ethernet Communication in BACnet/IP and MS-2102 Model Option "BAC/BAC1"

In Figure 10.1, BACnet/IP communication is added to MS-2102 heat tracing controller by MasterTrace Modbus to BACnet/IP gateway. The gateway (ex. BB3-7101 from Control Solutions, or FS-EZ1-MOD-BAC from Sierra Monitor) is interfacing a MS-2102 Modbus RTU control module to a BACnet/IP network. The gateway automatically polls the MS-2102 Modbus RTU control module at 9600 baud rate and stores the polling registers' content to their respective configured BACnet objects. The Modbus RS485 side can connect to the serial port of MS-2102 control module over long distances (up to 4000 feet). Through Ethernet cable, the gateway presents a BACnet device object to the BACnet/IP network. This single BACnet device object could consist of up to 5000 data objects, enough to cover every Modbus register in MS-2102. A BACnet management system, such as building automation system, BACnet network discovery tool, or BACnet explorer, may then use standard BACnet services such as Read Property to access of the content of a read-only data object/Modbus register, or Write Property to change the content of a readable & writable data object/Modbus register.

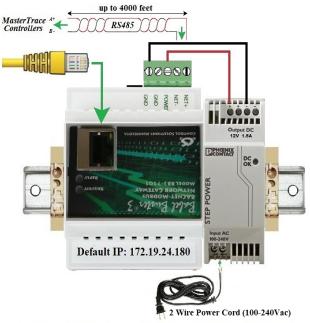
**BAC**, an additional option, has been added to the MS-2102 heat tracing controller model options to allow customers to purchase Nextron MS-2102 heat tracing controller with BACnet/IP communication capability. **BAC1** is another option for gateway mounted in a FRP enclosure. Refer to *Chapter 1 Product Overview* for MS-2102 Models.

Figure 10.1 BACnet/IP Communication



In a MS-2102 heat tracing control module with **BAC/BAC1** option, the MasterTrace Modbus to BACnet/IP gateway, as shown in *Figure 10.2*, is an assembled electronic unit, separated from MS-2102 module. It can be located as far as 4000 feet away from the module. To install it, use a 2 wire power cord to feed power to the unit and a RS485 cable to connect the unit and serial port of the MS-2102 module. An Ethernet cable is needed to connect the unit to Ethernet network. In this way, the gateway with default IP 172.19.24.180 joins the BACnet/IP communication network.

Figure 10.2 Configured Modbus to BACnet/IP gateway



Configured MasterTrace Modbus to BACnet IP Gateway

The gateway in Figure 10.2 is BB3-7101 or BB2-7010-01 or BB2-7010-01-10X from Control Solutions. There is a built-in web server "Babel Buster 3/2" with default IP 172.19.24.180 that can be accessed via web browser with user name and password. Through the web server, customer can configure various BACnet objects of interest. Three types of objects are commonly interested in MasterTrace heat tracing controller. They are analog input object, binary input object, and analog value object. (1) Analog input objects are created to poll their assigned modbus registers for heater measurement values such as RTD temperature, heater current, and ground fault current. (2) Binary input objects are created to reflect the binary signals of heater on/off status, heater alarm status, and specific alarm flags. They are constructed by extracting their specific bit within the heater status register 40110 (4 bytes) or heater alarm status register 40112 regularly polled from MS-2102 heat tracing module. (3) Analog value objects are created to monitor operation setpoints of interest, such as heater enable and heater setpoint. These

writable objects can be updated via the HMI interface in the building management system.

Coming out of Nextron factory, the following BACnet objects are configured in BB3-7101 or BB2-7010-01 or BB2-7010-01-10X Modbus to BACnet/IP gateway for Nextron-built MS-2102 heat tracing controller with model option *BAC/BAC1*.

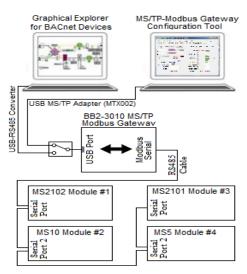
*Heater 1-1 Temperature (in unit of tenth of 1<sup>•</sup>C)* Heater 1-1 Current (in unit of 10mA) Heater 1-1 GF Current (in unit 1mA) Heater 1-1 On/Off status Heater 1-1 Alarm Status Heater 1-1 low temp alarm Heater 1-1 high temp alarm Heater 1-1 low current alarm Heater 1-1 high current alarm Heater 1-1 ground fault trip alarm Heater 1-1 ground fault alarm Heater 1-1 RTD A failure alarm Heater 1-1 RTD B failure alarm Heater 1-1 output SCR failure alarm Heater 1-1 Tracecheck GF alarm Heater 1-1 Tracecheck lo current alarm Heater 1-1 Tracecheck hi current alarm Heater 1-1 Tracecheck GF trip alarm Heater 1-1 Tracecheck SCR fail alarm Heater 1-1 low voltage alarm Heater 1-1 high voltage alarm Heater 1-1 high current trip alarm Heater 1-1 GF test alarm Heater 1-1 Enable Heater 1-1 Heater Setpoint Heater 1-2 Temperature Heater 1-2 Current Heater 1-2 GF Current Heater 1-2 On/Off status Heater 1-2 Alarm Status Heater 1-2 low temp alarm Heater 1-2 high temp alarm Heater 1-2 low current alarm Heater 1-2 high current alarm Heater 1-2 ground fault trip alarm Heater 1-2 ground fault alarm Heater 1-2 RTD A failure alarm Heater 1-2 RTD B failure alarm Heater 1-2 output SCR failure alarm Heater 1-2 Tracecheck GF alarm Heater 1-2 Tracecheck lo current alarm Heater 1-2 Tracecheck hi current alarm Heater 1-2 Tracecheck GF trip alarm Heater 1-2 Tracecheck SCR fail alarm Heater 1-1 low voltage alarm Heater 1-1 high voltage alarm Heater 1-2 high current trip alarm Heater 1-2 GF test alarm Heater 1-2 Enable Heater 1-2 Heater Setpoint

As mentioned above, field customers can use proper user name and password to access the built-in web server "Babel Buster 3/2" in the gateway with default IP 172.19.24.180 through any web browser to configure more BACnet objects of their interests on other additional MasterTrace heat tracing control modules, as long as (1) serial ports of all control modules are connected in daisy-chain fashion; (2) each control module is with a unique module number and at 9600 baud rate; (3) the total number of objects does not exceed the limit of 5000/1000.

#### Serial Communication in BACnet MS/TP network

In Figure 10.3, serial communication in BACnet MS/TP protocol is added to a group of 4 MasterTrace heat tracing control modules by Babel Buster BB2-3010, a BACnet MS/TP to Modbus Serial gateway from Control Solutions. The gateway has 2 sides. The Modbus Serial side can connect to the serial ports of MasterTrace control modules over long distances (up to 4000 feet) at 9600 baud rate. The USB Port side connects to MS/TP-Modbus gateway configuration tool from Control Solutions through a special USB MS/TP adapter (MTX002). This configuration tool is a software interface where customers can configure various BACnet objects. Three types of objects are commonly interested in MasterTrace heat tracing modules. They are analog input object, binary input object, and analog value object. (1) Analog input objects are created to poll their assigned modbus registers for heater measurement values such as RTD temperature, heater current, and ground fault current. They are non-commandable objects. (2) Binary input objects are created to reflect the binary signals of heater on/off status, heater alarm status, and specific alarm flags. They are constructed by extracting their specific bit within the heater status register 40110 (4 bytes) or heater alarm status register 40112 regularly polled from MasterTrace heat tracing modules. (3) Analog value objects are created to monitor operation setpoints of interest, such as heater enable and heater setpoint. They are commandable objects. The BB2-3010 supports up to 300 non-commandable objects, or up to 135 commandable objects, or a mix in between.

#### Figure 10.3 BACnet MS/TP Communication

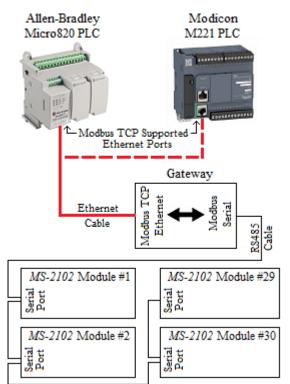


Upon successful configuration, the gateway will constantly update all the configured objects with data polled from their assigned modbus registers in the targeted MasterTrace control modules at the specified intervals. Through a USB-RS485 converter (or MTX002 in passthru mode) on its USB port, the gateway presents a number of live BACnet objects to the BACnet MS/TP network. A BACnet MS/TP supervisory controller or graphical explorer for BACnet devices may then use standard BACnet services such as Read Property to access of the content of a read-only data object/Modbus register, or Write Property to change the content of a readable & writable data object/Modbus register.

# Ethernet Communication in Modbus TCP and MS-2102 Model Option "ETH/ETH1"

In *Figure 10.4*, Ethernet communication in Modbus TCP is added to MasterTrace heat tracing control modules by Modbus TCP Ethernet to Modbus Serial gateway. The gateway (ex. GC-NET485-MB from Grid Connect) is a Modbus RS485 serial to Modbus TCP Ethernet converter. The RS485 side can connect to the serial port 2 of MasterTrace control modules over long distances (up to 4000 feet). The Ethernet side converts the serial Modbus

Figure 10.4 Modbus TCP Ethernet Communication



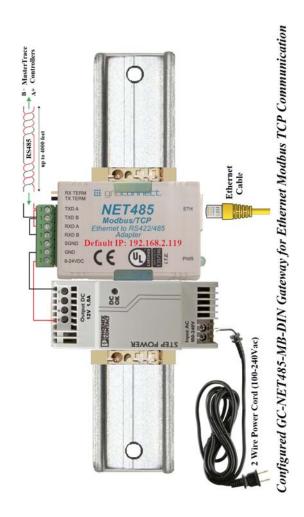
data stream to Modbus TCP Ethernet packets.

Connect a PLC or Automation system to the gateway through its Ethernet port and use it as the Master in the network. You can program the Master according to MasterTrace Modbus Communication Protocol to write/read data to/from MasterTrace control modules over Ethernet from anywhere in the plant as long as the Ethernet port on the PLC or Automation system is Modbus TCP supported and is assigned to an IP address that is different to the IP addresses of the gateway and other devices in the Ethernet network. Most of PLCs and Automation systems such as Micro820 from Allen-Bradley and M221 from Modicon do have this kind of Ethernet port as built-in.

**ETH**, an additional option, has been added to the MS-2102 heat tracing controller model options to allow customers to purchase Nextron MS-2102 heat tracing controller with Ethernet Modbus TCP communication capability. **ETH1** is another option for gateway mounted in a FRP enclosure. Refer to *Chapter 1 Product Overview* for MS-2102 Models.

In a MS-2102 heat tracing control module with **ETH/ETH1** option, the Modbus TCP Ethernet to Modbus Serial gateway as shown in *Figure 10.5* is an assembled

Figure 10.5 Configured Ethernet to Modbus Serial Gateway



electronic unit, separated from MS-2102 module. It can be

located as far as 4000 feet away from the module. To install it, use a 2 wire power cord to feed power to the unit and a RS485 cable to connect the unit and serial port of the MS-2102 module. Coming out of Nextron factory, the IP address of the gateway (GC-NET485-MB from Grid Connect) has been assigned to 192.168.2.119, and its serial port baud is set to 1200. An Ethernet cable is needed to connect the unit to Ethernet network. In this way, the gateway joins the Ethernet communication network of the PLC or Automation system.

#### An Important Note on Ethernet Gateways

In *Figure 10.2 and 10.5*, the same power supply from Phoenix Contact (Phoenix Contact 2868567, 8-24Vdc output, Din Rail, Class 1 Div 2) is used in both units of assembled Ethernet gateway. Its input power voltage range is 100-240Vac. This makes it possible to locate the gateway unit beside the MS-2102 module and utilize the power from MS-2102 to feed the power supply from Phoenix Contact, as long as the MS-2102's input voltage is in a range of 100-240Vac. Use a pair of 14 AWG wires to connect MS-2102's terminal 2 & 3 to terminal L(+) & N(-) of the Phoenix Contact power supply, respectively. In this scenario, due to the limitation of maximum Ethernet cable length, the gateway can only be located less than 100 meters away from the Ethernet network hubs.

# Warranty

The manufacturer warrants each control that it manufactures to be free from defective material or workmanship for a period of 12 months from date of purchase.

Under this warranty, the obligation of the manufacturer is limited to repairing or replacing the defective control at its option, when returned to the manufacturer's factory with shipping charges prepaid.

If failure has been caused by misuse, incorrect application or alteration of the control, this warranty will be void.

UNLESS SPECIFICALLY PROVIDED FOR IN WRITING IN THIS WAR-RANTY, EACH CONTROL IS PROVIDED WITHOUT ANY WARRANTY OF ANY KIND EITHER EXPRESSED OR IMPLIED. IN PARTICULAR, WITHOUT LIMITING THE GENERALITY OF THE FOREGOING, THE FOLLOWING IMPLIED WARRANTIES AND CONDITIONS ARE EXPRESSLY DIS-CLAIMED:

- a). ANY IMPLIED WARRANTY OR CONDITION THAT THE CON-TROL WILL MEET YOUR REQUIREMENTS.
- b). ANY IMPLIED WARRANTY OR CONDITION THAT THE OPERA-TION OF THE CONTROL WILL BE UNINTERRUPTED OR ERROR FREE; AND
- c). ANY IMPLIED WARRANTY OR CONDITION OF MERCHANTABILITY OR FITNESS FOR A PARTICULAR PURPOSE.

The user shall be made aware that if the equipment is used in a manner not specified by the manufacturer, the protection provided by the equipment may be impaired.

# MASTERTRACE<sup>TM</sup> HEAT TRACING CONTROL

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